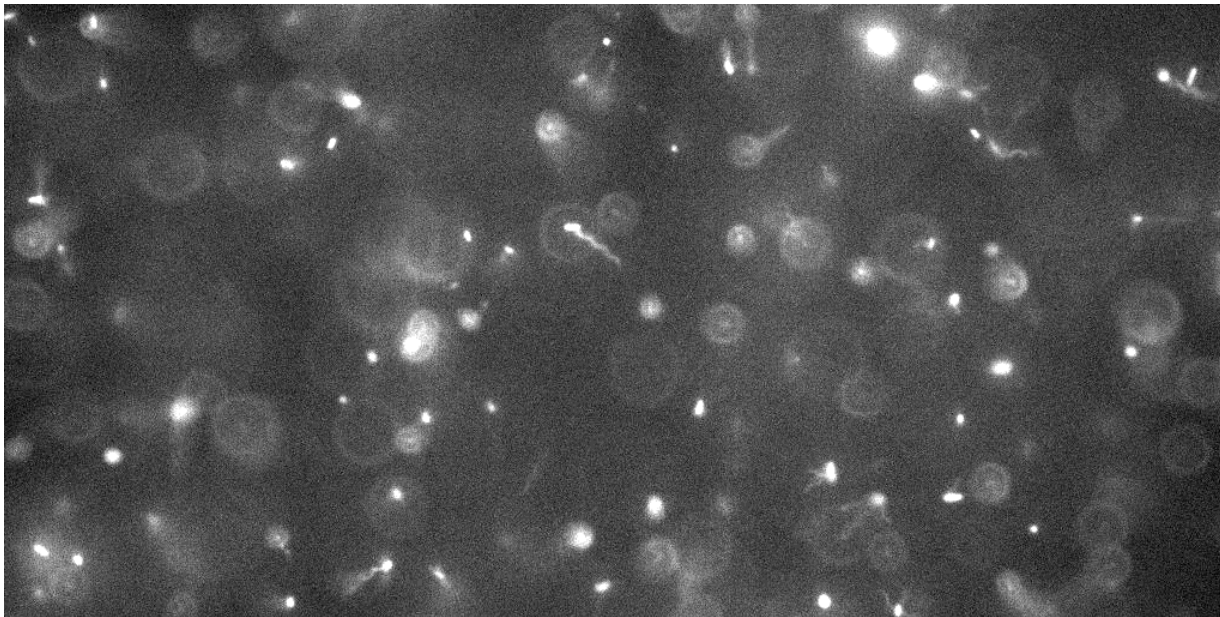


Eric Clément [eric.clement@upmc.fr](mailto:eric.clement@upmc.fr)

Active Fluids Group at the PMMH-ESPCI, Paris

## Some elements on bacteria motility



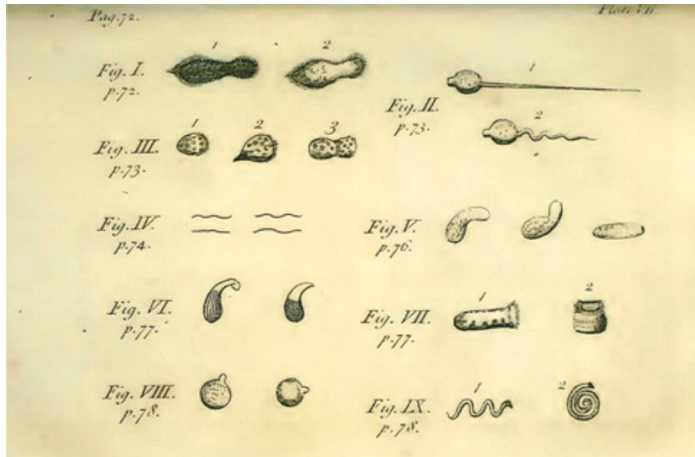
# The first microbiologist !



Animalcula



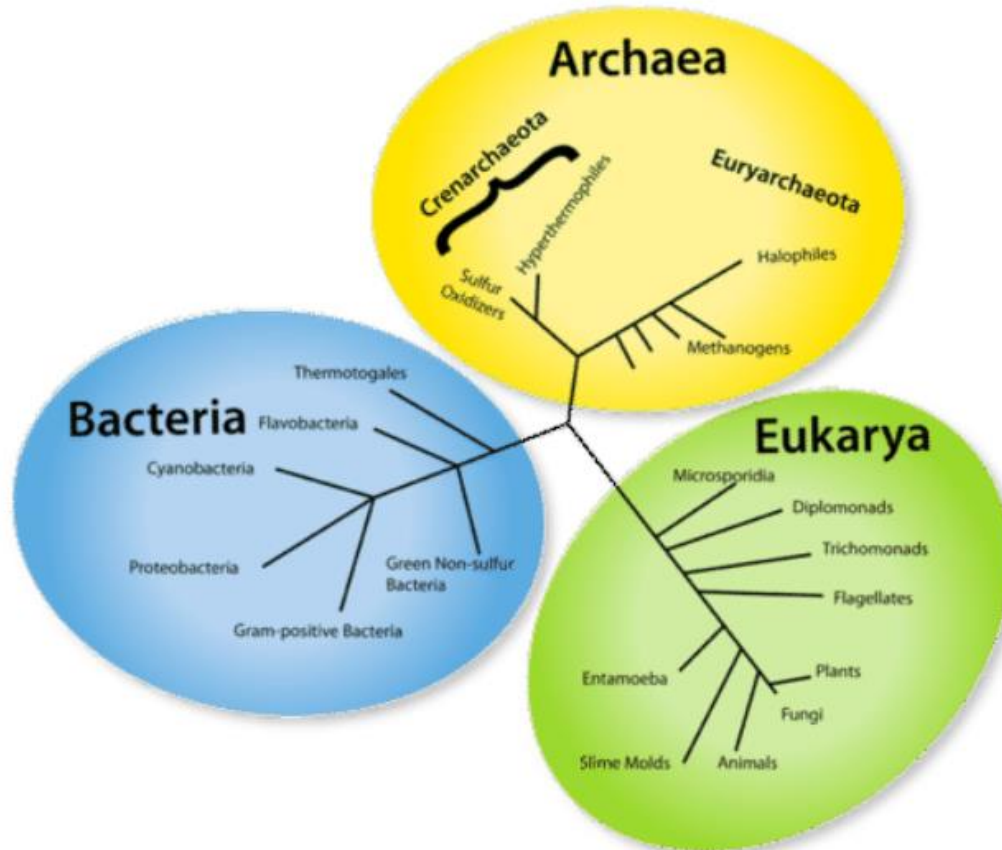
Antoni van Leeuwenhoek (1632-1723)  
father of protozoology and bacteriology



- ❑ Discovery of « little animals »
- ❑ First description of autonomous motion by the « *rotation of small wheels issuing out of their bodies* »

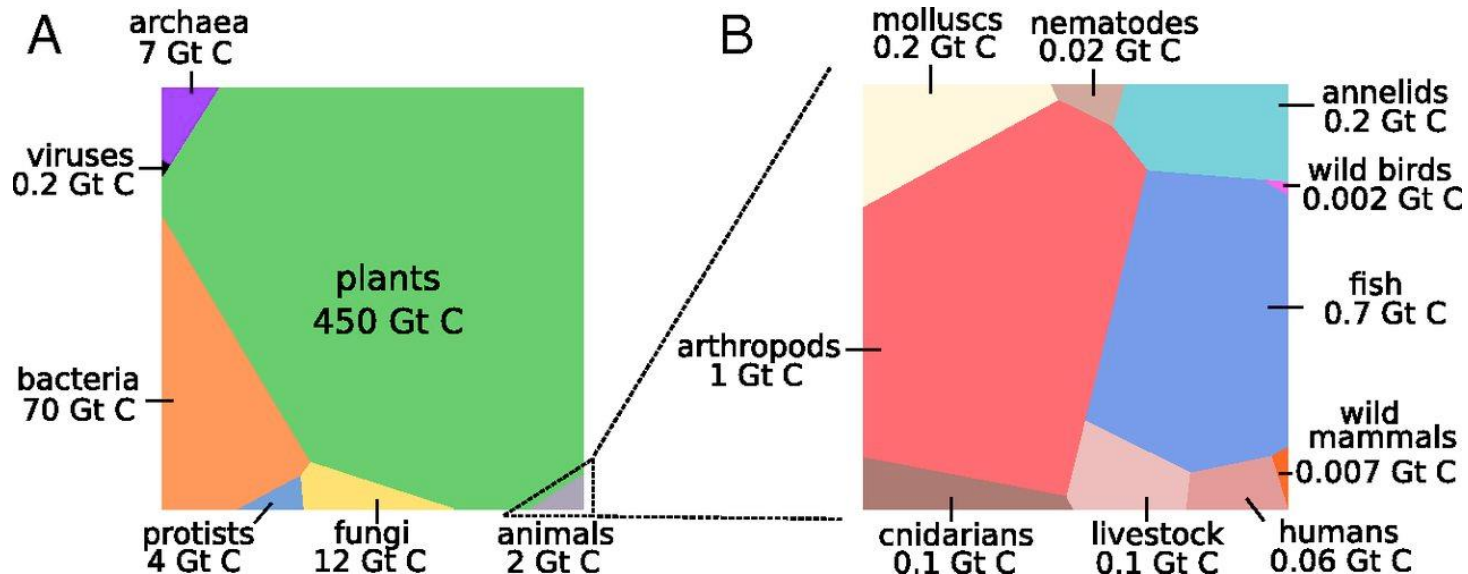
van Leeuwenhoek Lett. Roy. Soc., **24** (1705)  
(2 citations)

# The three kingdoms of life (on earth)



# Bacteria

- ❑ Bacteria are micro-organisms (typically 1-2  $\mu\text{m}$ ) ubiquitous in nature
- ❑ Appeared 3.8 billion years ago! => strong capacity of **adaptation** to diverse environments
- ❑ ~30,000 formally named species (*i.e.* for which the physiology has been studied) Dykhuizen, *Proc. Calif. Acad. Sci.*



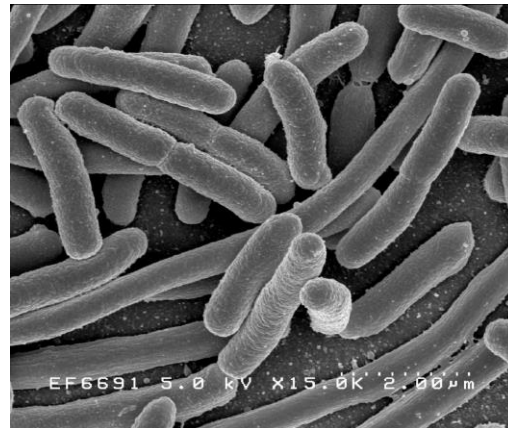
The Biomass distribution on Earth Bar-On *et al.*, *PNAS* (2019)

# Bacteria and Human Beings

- ❑ Bacteria are essential to human life : 90% of our body is composed by non-human cells among which bacterial cells.  
*Turnbaugh et al., Nature (2007)*
- ❑ *E. coli* is a common example of bacteria living in the human gut
- ❑ We often use bacteria in industrial processes like cheese fabrication or wine malolactic fermentation



*Cheese*



*Escherichia coli*



*Vine*

# Bacteria populations dynamics

Soil ecology

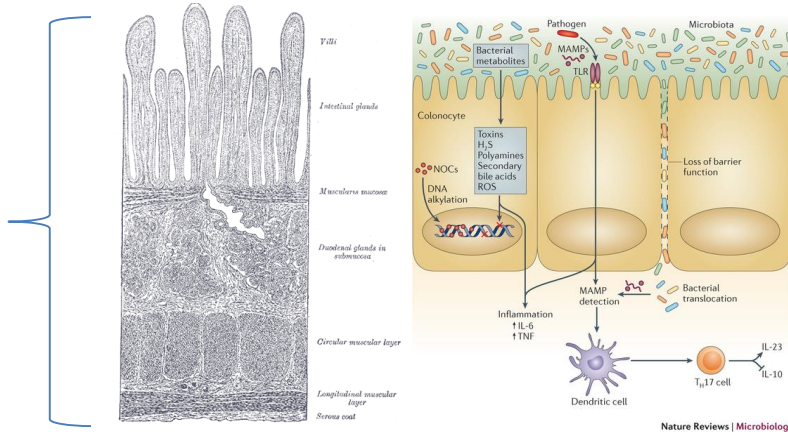


CO2 production/storage

Biodiversity (symbiosis with plant roots, fungi)

Microbiota

Intestin wall



Key role in many pathologies

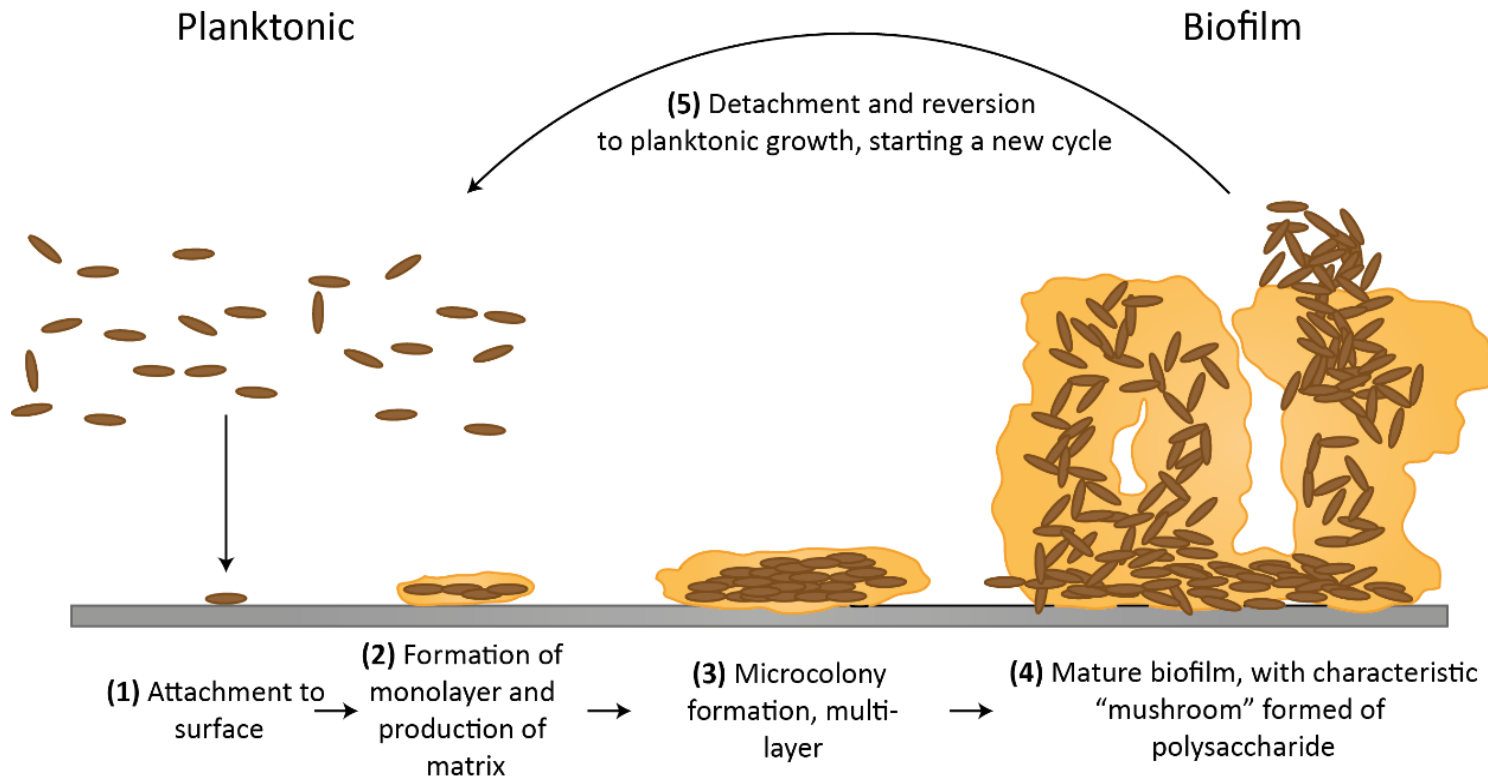
Chronical diseases

Obesity

Cancer

New therapeutic pathways

# Planktonic state vs biofilm



Hollmann et al. *\_Brit.Soc.Immun*

□ Planktonic state is essential to bacteria in order to explore and colonize environments

# Motile bacteria

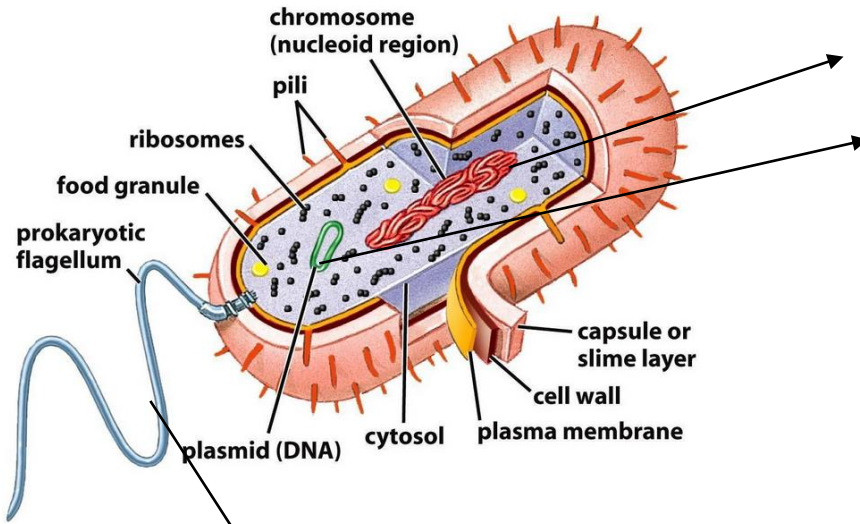
Genetics, epigenetics



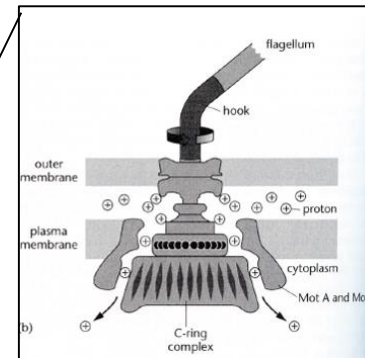
Adaptative evolution, mutations

Synthetic biology

Programmable target function



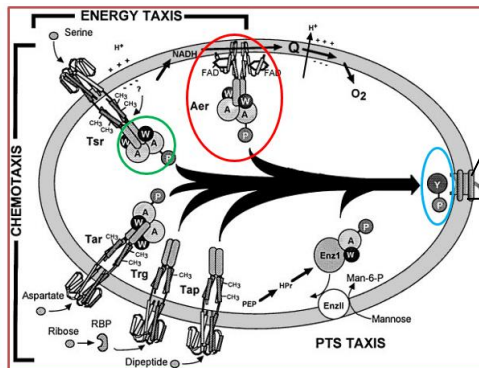
Proton gradient motor



Motility



Biochemical machinery



Chemical environment



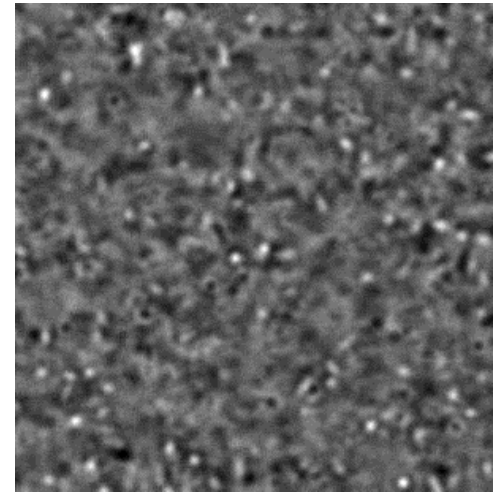
Attractant/repellent  
Redox reactions





# A model for « active colloids »

- ❑ Revisit the statistical physics of colloids
- ❑ Emergence of new universality classes
  - Symmetry of microscopic interactions
  - Range of interactions
- ❑ Hydrodynamic description
  - Macroscopic constitutive relations
  - Transport relations
- ❑ See for a practical introduction : Schwarz-Linek et al., Colloids and Surfaces B: Biointerfaces, **137,2** (2016).

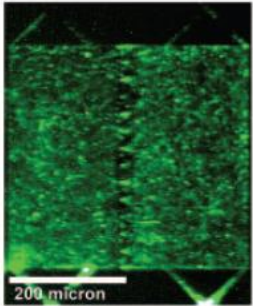


# Many novel effects

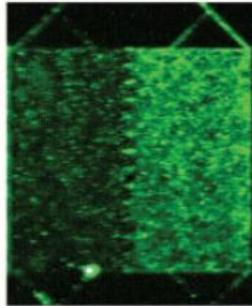
(some examples)

Diffusion rectification

$t = 0$

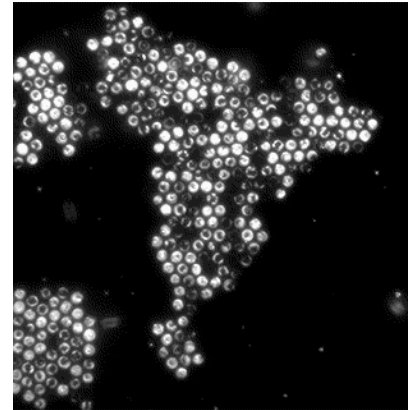


$t > 0$



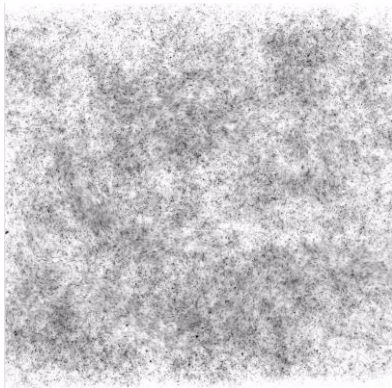
Galajda et al. J. of Bact., **189** 8704 (2007)

Living crystals



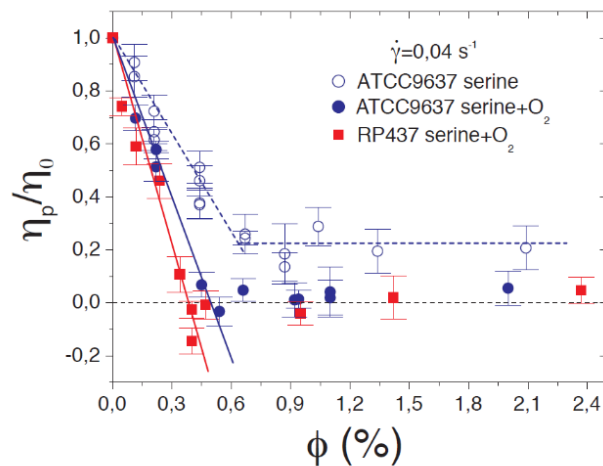
Petroff et al. PRL **114**, 158102 (2015)

Collective motion



Martinez et al. PNAS **117**, 2326 (2020)

« Superfluid »



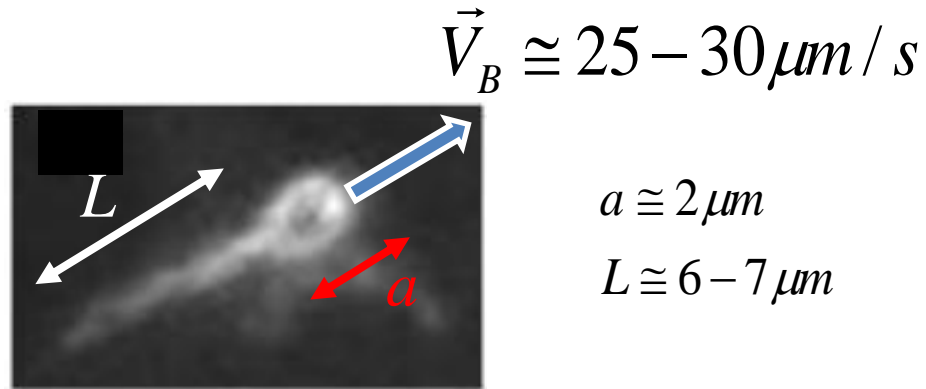
Lopez et al. PRL. **115**, 028301 (2015)

Bacteria swarms activate gear



Sokolov et al. PNAS **107**, 969 (2010)

# Hydrodynamics of swimming



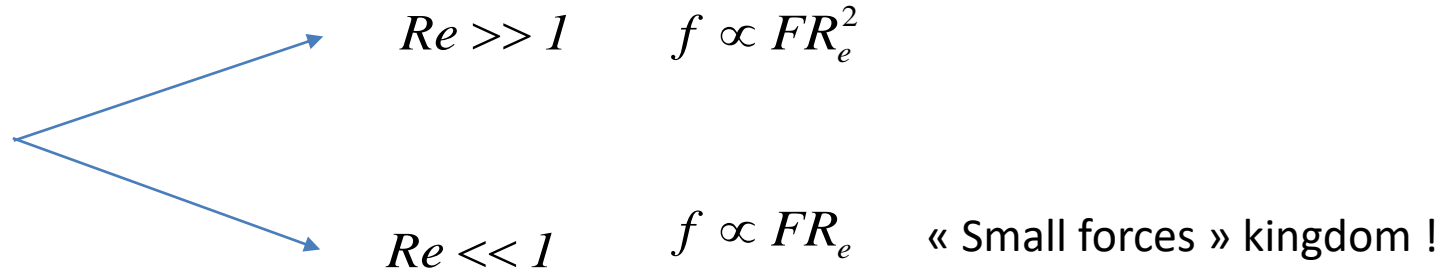
Reynolds number  $\text{Re} = \frac{\text{Inertial forces}}{\text{Viscous forces}} = \frac{\rho a V_B}{\eta} \cong 10^{-4}$

□ Low Reynolds microswimmer

# The small forces kingdom

$$F = \frac{\eta^2}{\rho}$$

Intrinsic force scale for a viscous fluid  
 $F = 10^{-9} \text{ N}$  for water



□ You need to develop forces of order  $f = Re F$  to propel or move an object in a viscous fluid

$$f \cong 10^{-13} \text{ N}$$

Ex



$$a = 1 \mu\text{m}$$

$$V = 30 \mu\text{m} / \text{s} \Rightarrow Re \approx 10^{-4}$$



« Coasting time »  $\tau_\delta = \frac{\rho a^2}{\eta} = 10^{-6} \text{ s}$

« Coasting length »  $\delta = V\tau \cong 10^{-11} \text{ m}$

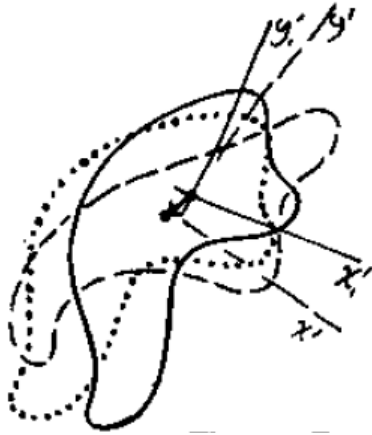
# Stokes equations $Re = 0$

$$-\vec{\nabla} p + \eta \nabla^2 \vec{u} = \vec{0}$$

$$\vec{\nabla} \cdot \vec{u} = 0$$

No time explicitly !

+ Instantaneous  
boundary conditions



- Swimming means « move your body in a cyclic manner and hope for a net motion »
- The distance travelled by the swimmer between two different surface configurations does not depend on the rate at which the surface deformation occurs, but only on the geometry of the intermediate shapes.

# The « scallop theorem »



E.M.Purcell, *Am. J. Phys.* 45, 11 (1977)

Purcell, *PNAS*, 94 11307 (1997)

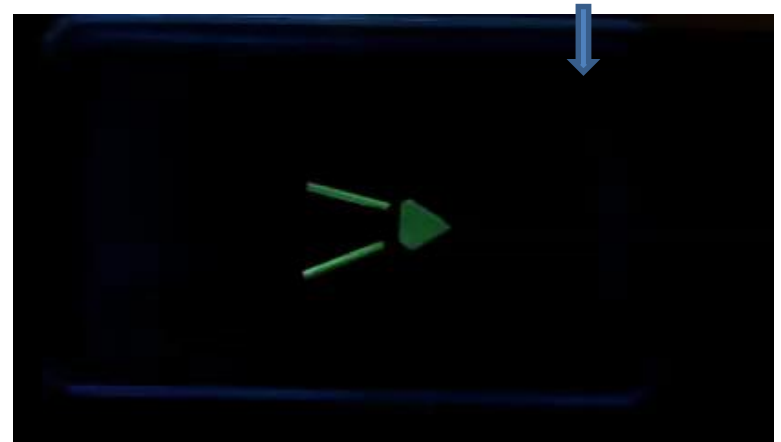
$Re = 10^3$

$L = 10 \text{ cm}$

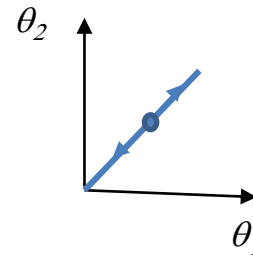
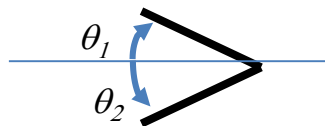


$Re \ll 1$

$L = 10 \text{ cm}$



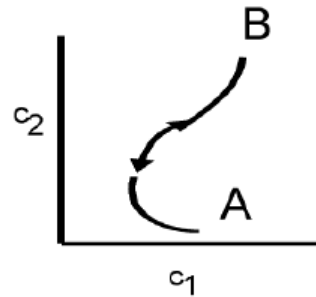
Qiu et al *Nature Com* (2014)



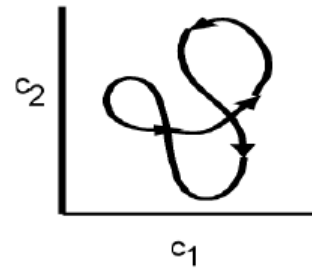
Reversible motion

# The « scallop theorem » or reciprocal motion theorem

Ex. (C1, C2) 2D configuration space



(a)

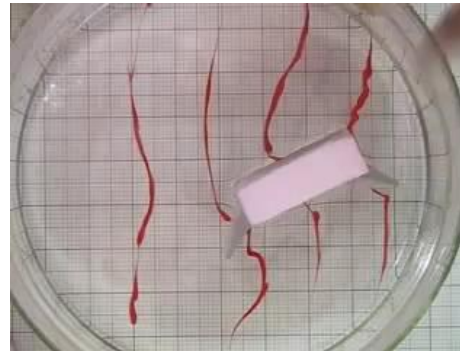
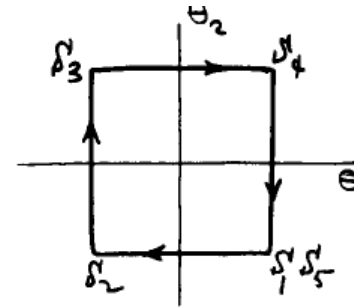
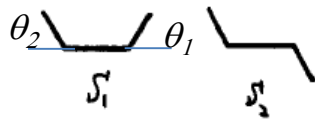


(b)

(a) Reciprocal motion  
(b) Non-reciprocal motion

« *If the standard movement of a periodic Stokesian locomoter is reciprocal, steady locomotion with non-zero velocity is not possible.* » (Purcell 1977)

# A minimal swimmer model the 3 – link swimmer (Purcell 1977)



Peko Hosoi MIT



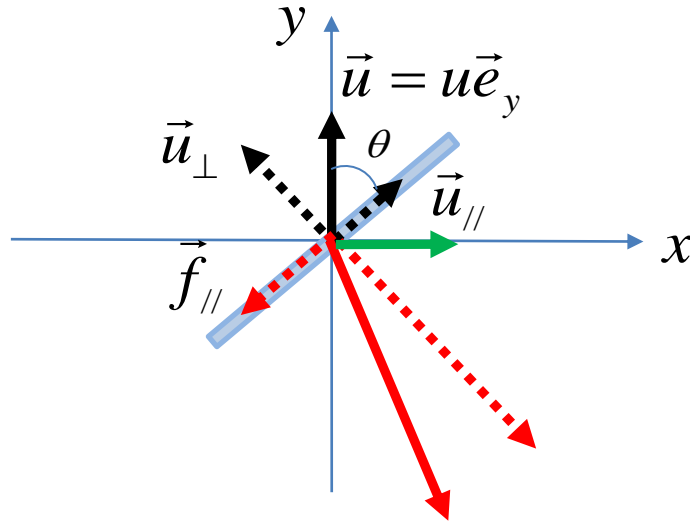
# Helical swimming



G.I. Taylor movie series on hydrodynamics

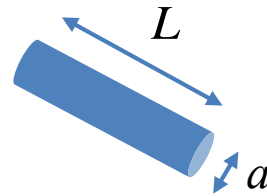
- The corkscrew strategy is efficient at zero  $Re$

# Key concept



$\vec{f}_{prop} = \eta(\xi_{\perp} - \xi_{//})u \sin\theta \cos\theta \vec{e}_x$ 
**Force/length** along  $x$  direction

Ex.



$$\xi_{\perp} = 2\xi_{//} = \frac{4\pi}{\ln 2L/a}$$

□ Drag anisotropy

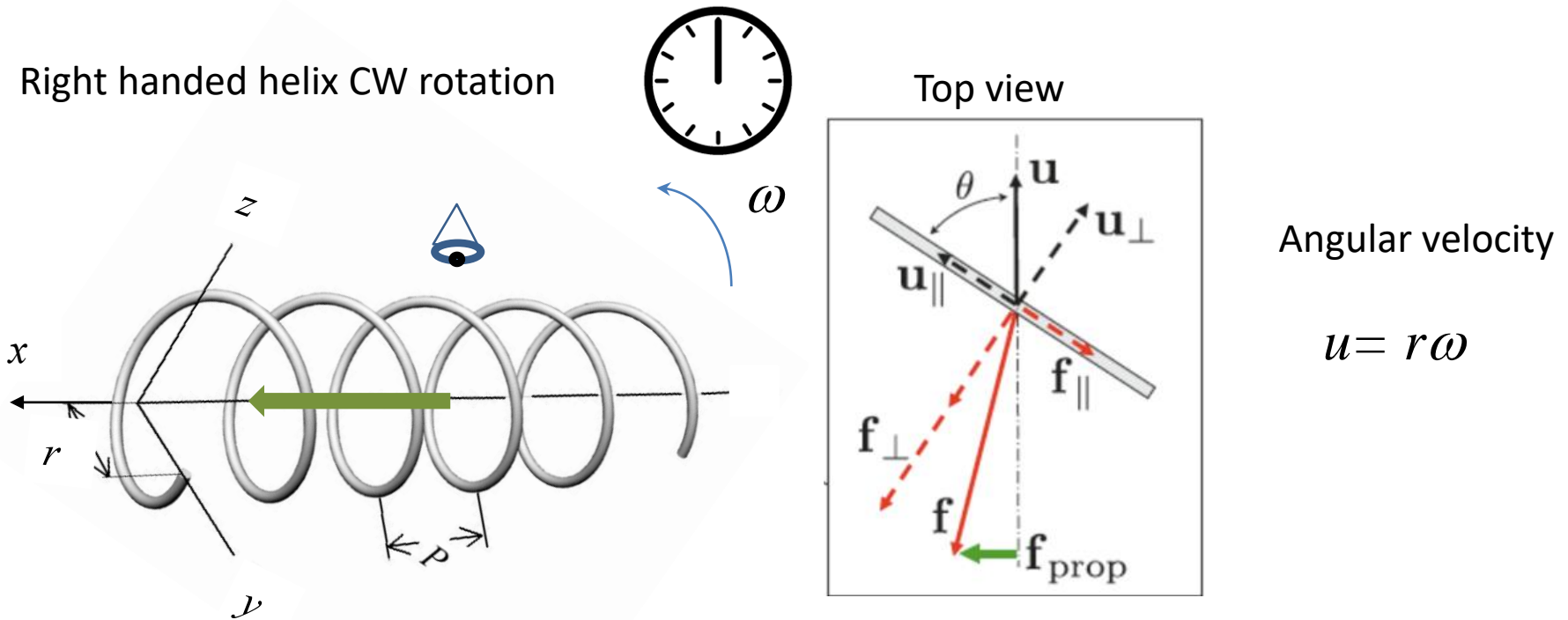
**Left-handed  
helix**



**Right-handed  
helix**



# Helical propulsion

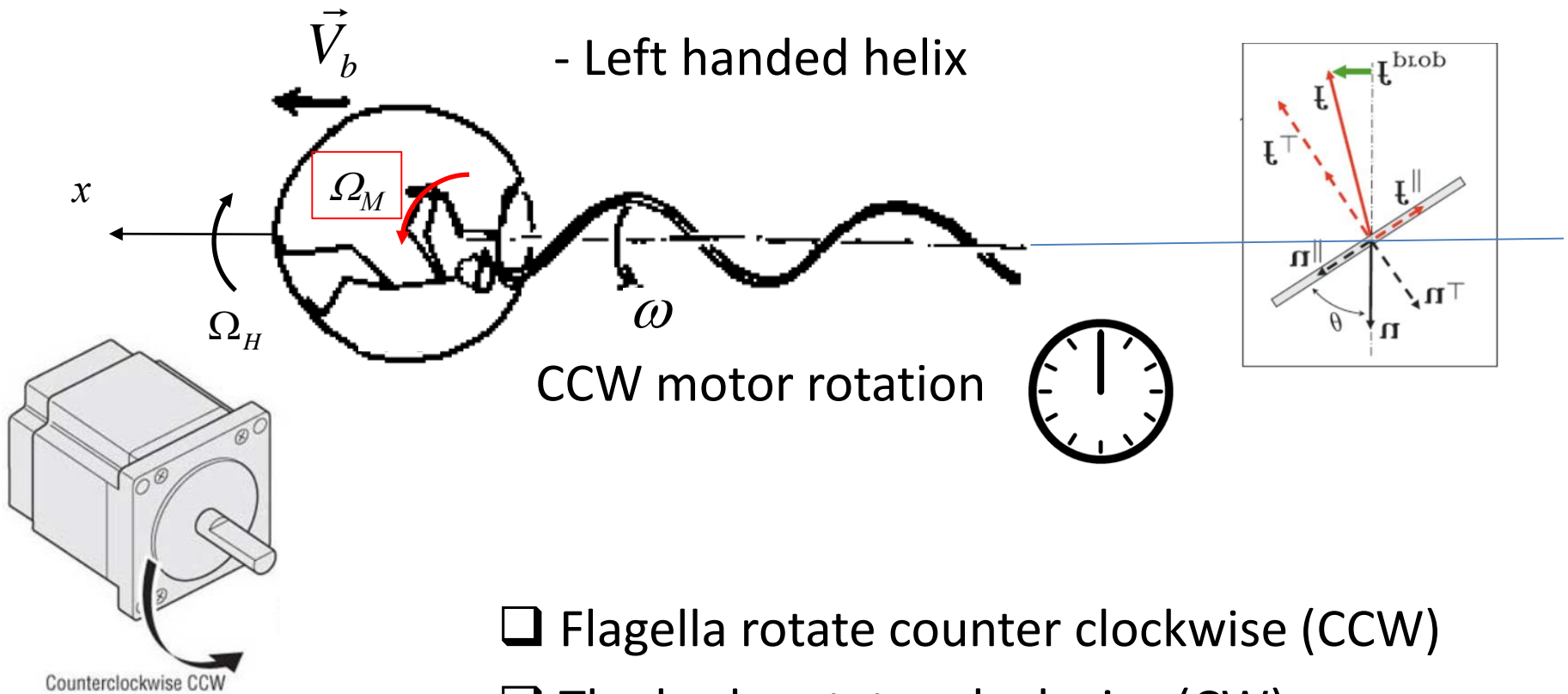


□ Propulsive force / length

$$\vec{f}_{prop} = \eta(\xi_{\perp} - \xi_{\parallel})u \sin \theta \cos \theta \vec{e}_x$$

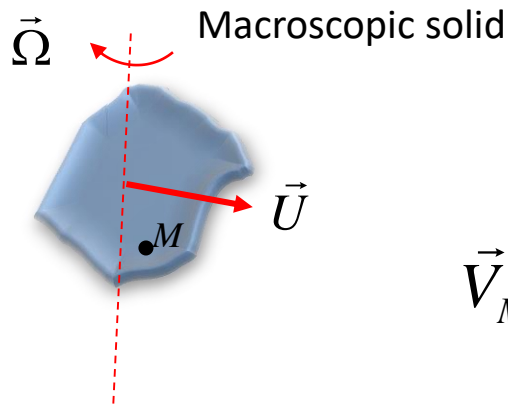
# Model for a self-propelled bacterium

Purcell PNAS **94** 11307 (1997)



- Flagella rotate counter clockwise (CCW)
- The body rotates clockwise (CW)

# The resistance matrix $Re = 0$



$\vec{F}$  Force on the solid

$\vec{U}$  Translation velocity

$\vec{T}$  Torque on the solid

$\vec{\Omega}$  Angular rotation rate

$$\vec{V}_M = \vec{U} + \vec{\Omega} \times \vec{r}$$

$$\begin{pmatrix} \vec{F} \\ \vec{T} \end{pmatrix} = -\eta \begin{pmatrix} \overline{\overline{A}} \vec{U} + \overline{\overline{B}} \vec{\Omega} \\ {}^t \overline{\overline{B}} \vec{U} + \overline{\overline{C}} \vec{\Omega} \end{pmatrix}$$

$\overline{\overline{A}}, \overline{\overline{B}}, \overline{\overline{C}}$

Rank 2 tensor (3x3 matrices)

$$[\overline{\overline{A}}] = L, [\overline{\overline{B}}] = L^2, [\overline{\overline{C}}] = L^3$$

Physical dimensions

General properties

$$A_{ij} = A_{ji}, C_{ij} = C_{ji}$$

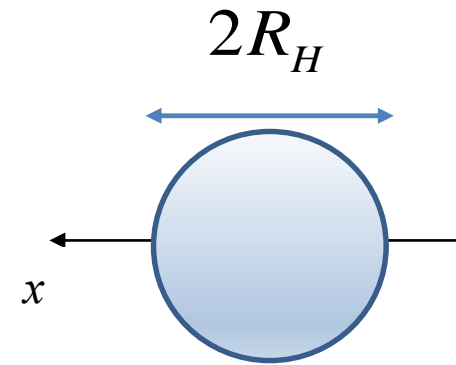
Physical symetries

## Resistance matrix for the sphere

$$\begin{pmatrix} F \\ T \end{pmatrix} = -\eta \begin{pmatrix} A & 0 \\ 0 & C \end{pmatrix} \begin{pmatrix} U \\ \Omega \end{pmatrix}$$

$$A = 6\pi R_H$$

$$C = 8\pi R_H^3$$



## Resistance matrix for the helix (left handed)

$$\begin{pmatrix} F \\ T \end{pmatrix} = -\eta \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} U \\ \omega \end{pmatrix}$$



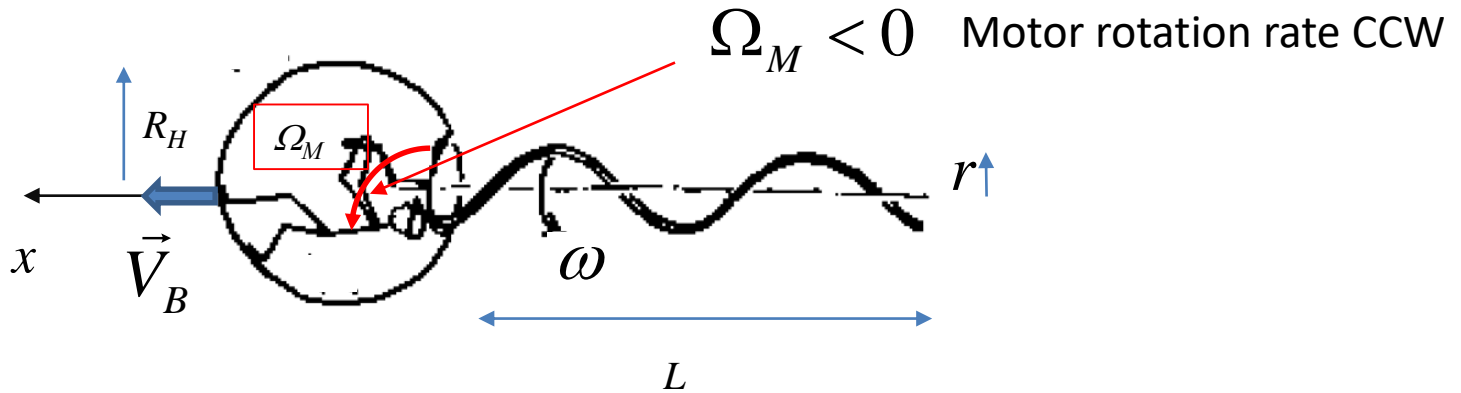
$$a \approx \xi_{//} L$$

$$b \approx \alpha (\xi_{\perp} - \xi_{//}) r L$$

$$c \approx \xi_{\perp} r^2 L$$

Helix angle  $\alpha \ll 1$

# Swimming velocity



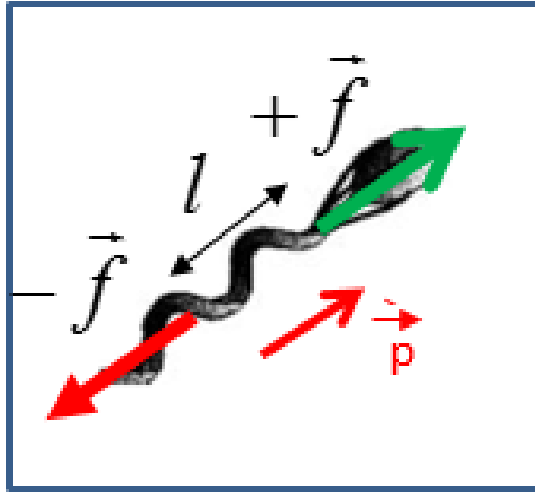
$$V_B = -\frac{bC}{(A+a)(C+c)-b^2} \Omega_M \propto (\xi_{\perp} - \xi_{\parallel}) \Omega_M$$

Motor rotation rate

Drag anisotropy



# Swimmers as force dipoles



An elliptical cow !

# Stokeslet solution $Re=0$

Stokes equations

$$-\bar{\nabla}P + \eta \nabla^2 \bar{u} + \bar{F} = \bar{0}$$

$$\bar{F}(\bar{r}) = \bar{f} \delta_{\bar{r}-\bar{r}'}$$

One force singularity in  $\bar{r}'$

$$\bar{\nabla} \cdot \bar{u} = 0$$

$$\bar{u} = \bar{\bar{G}}(\bar{r} - \bar{r}') \bar{f}$$

$$P = \frac{\bar{f} \cdot (\bar{r} - \bar{r}')}{4\pi r^3}$$

Oseen tensor

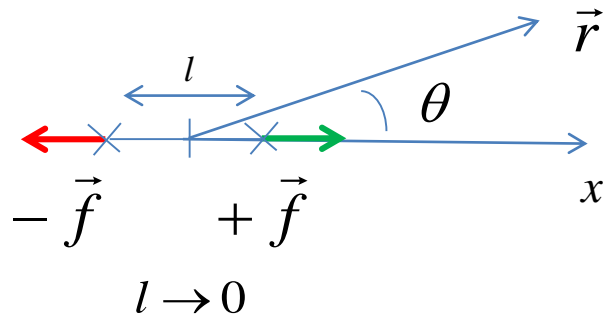
$$\bar{\bar{G}}(\bar{r}) = \frac{1}{8\pi\eta_0} \left( \frac{\bar{1}}{r} + \frac{\bar{r}\bar{r}}{r^3} \right)$$

$$u \propto \frac{f}{\eta_0 r}$$

□ Linear superposition of stokeslets -> solution of Stokes equation

$$\bar{u} = \sum_i \bar{\bar{G}}(\bar{r} - \bar{r}_i) \bar{f}_i$$

# Moving stresslets $Re=0$



$$u \propto \frac{\sigma_0}{\eta_0 r^2}$$

No net force on the fluid

$$\vec{u}(\vec{r}) = \frac{fl}{8\pi\eta_0 r^3} (-1 + 3\cos^2\theta)\vec{r}$$

$$P = 2\eta \frac{fl}{r^3} [-1 + 3\cos^2\theta]$$

$$\sigma_0 = fl$$

Dipole strength

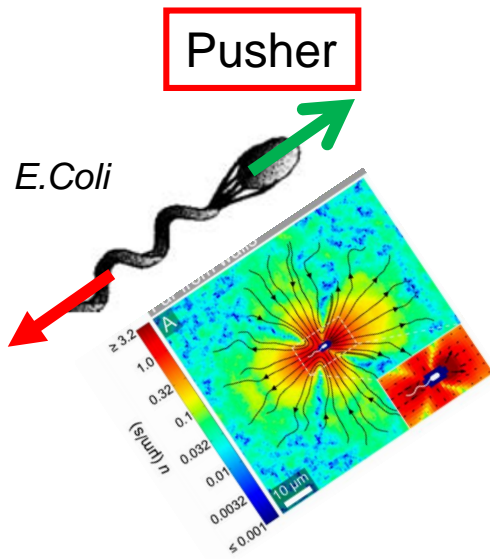


$$\sigma_0 \propto \eta_0 V_B l^2$$

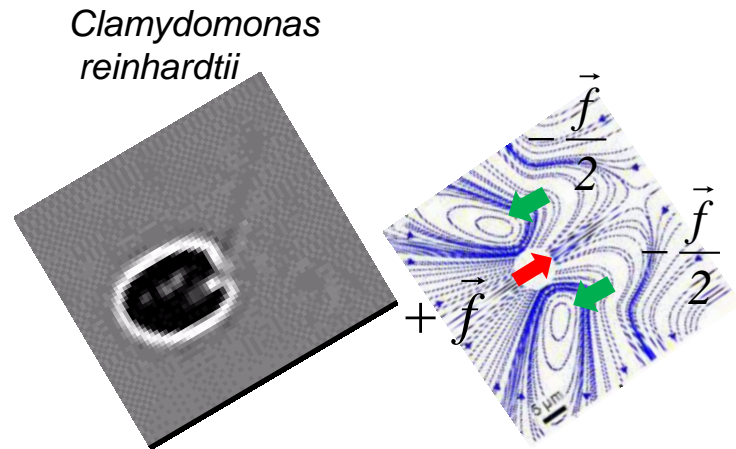
Swimming activity

# Force dipole sign

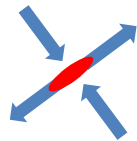
(Far field)



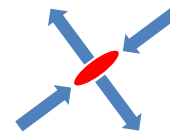
K.Drescher et al. PNAS **108**, 10945 (2011)



K.Drescher et al. PRL **105**, 168101 (2010)

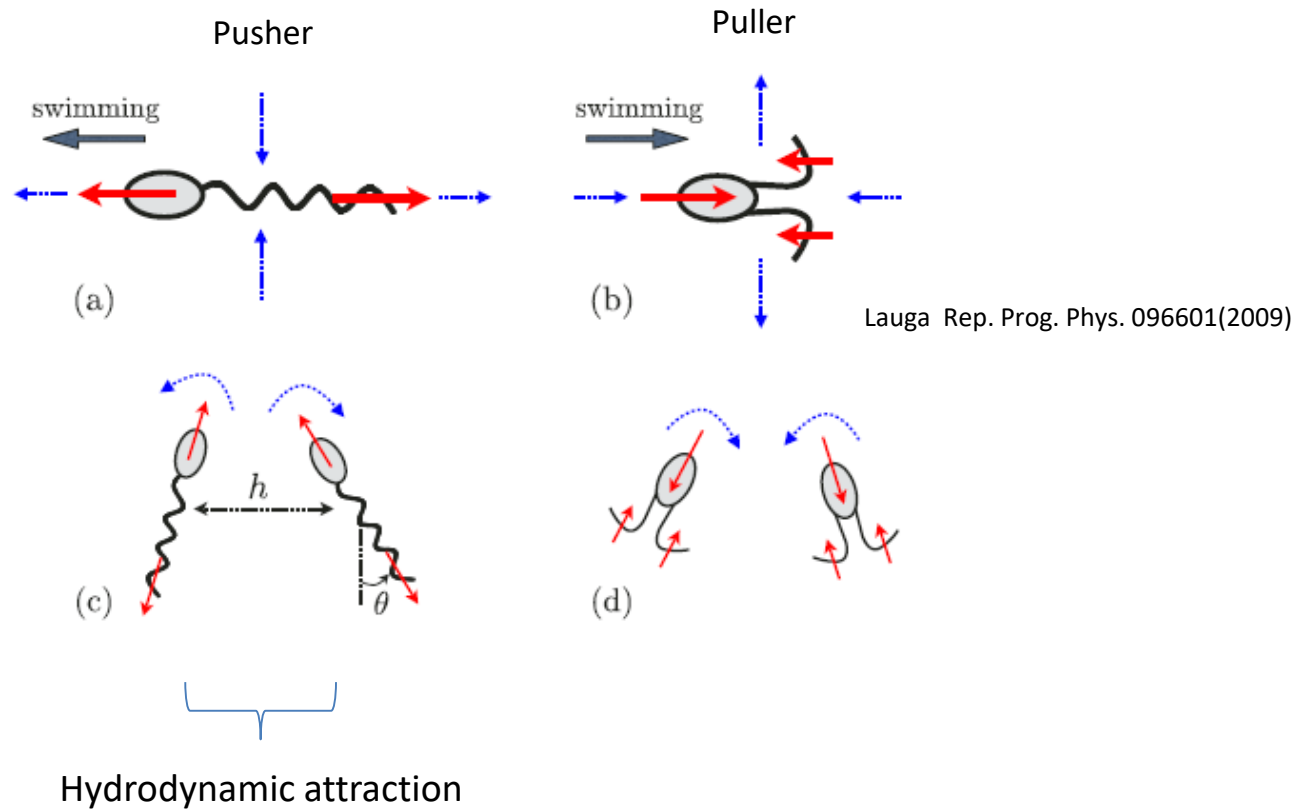


Extensile



Contractile

# Swimmers in interaction





## ☐ Pushers favor nematic alignment

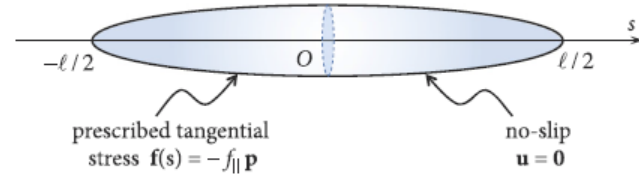
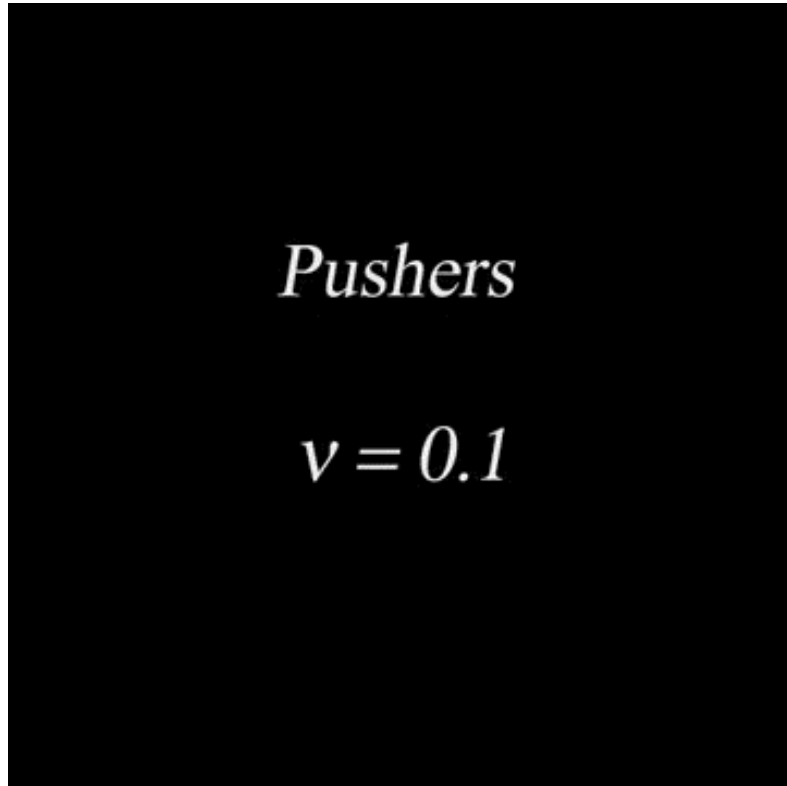
- long range hydrodynamic attraction
- short range hard-core (elongated particle )



## ☐ pullers favor line forming

- long range hydrodynamic attraction
- short range hard-core (spherical particle )

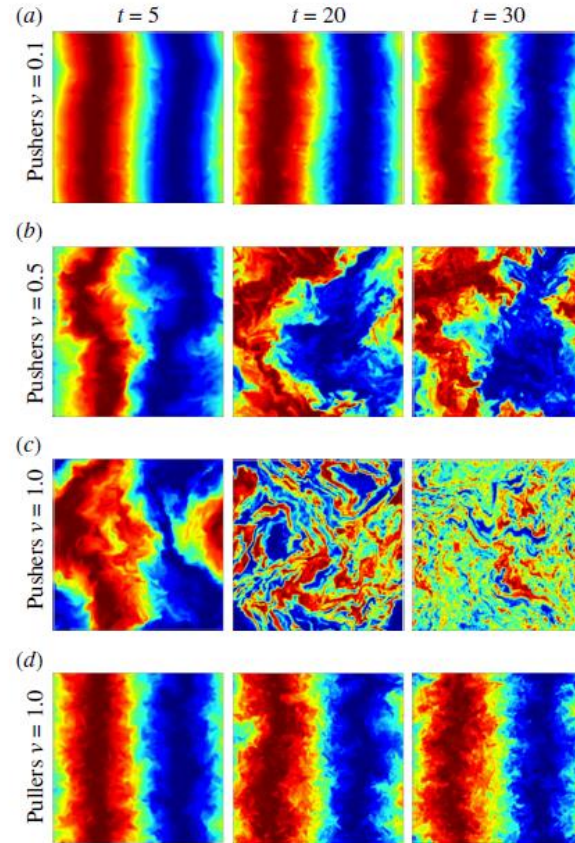
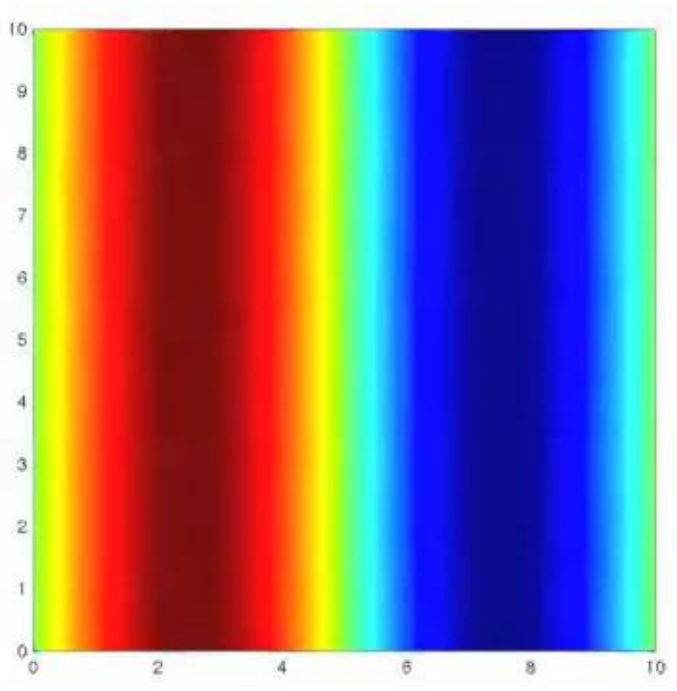
# 3D slender-body numerical simulation



Excluded volume fraction

$$v = n \frac{\pi}{6} l^3$$

# Mixing of a passive scalar field



Strong mixing properties of pushers

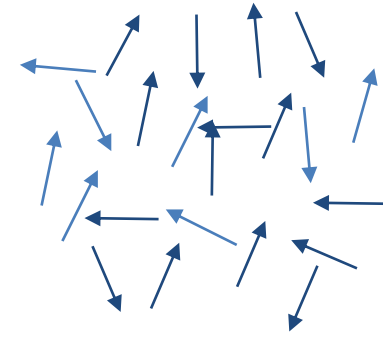
Moderate mixing of pullers



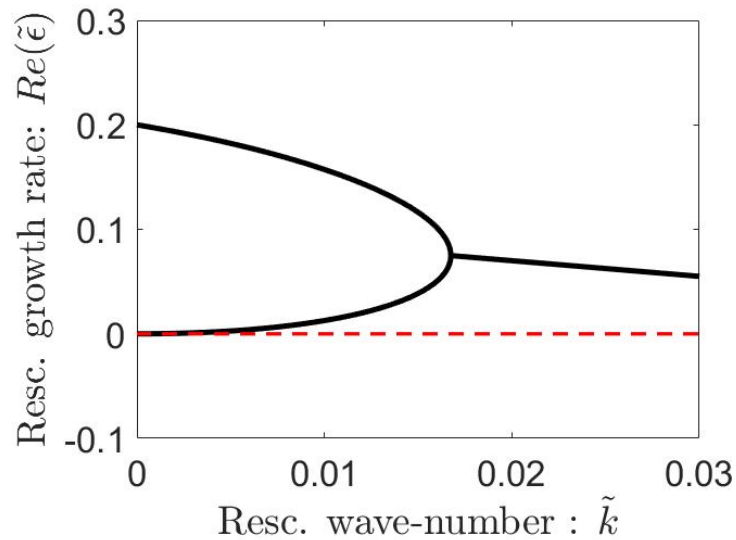
# Active dipoles hydrodynamics

$\sigma_0$  Dipolar strength  
 $n = \phi l^{-3}$  Dipoles density

No noise !



Velocity fluctuations growth rate:  $\delta \widetilde{U}_k \propto e^{i\vec{k}\vec{r}} \exp(\varepsilon_k \tilde{t})$



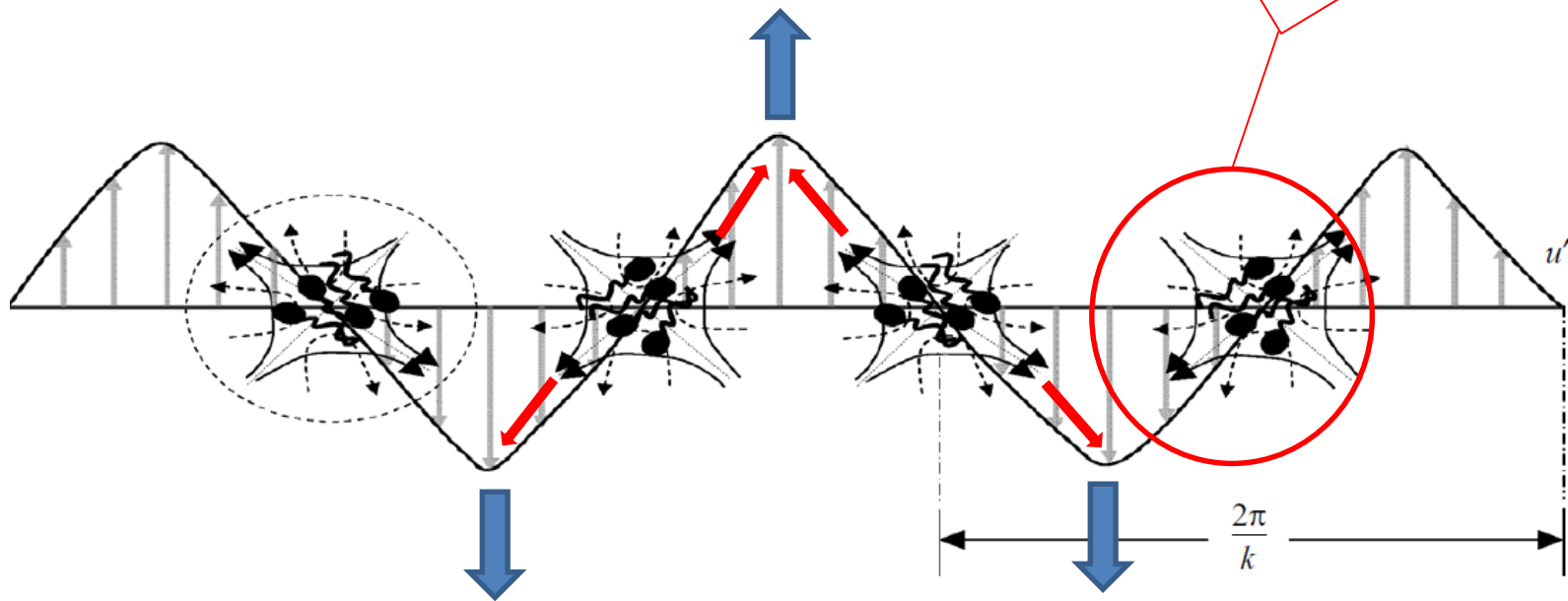
Fastest growing linear mode  
 $Re(\varepsilon(k)) > 0$  (unstable)

Saintillan and Shelley, Phys. Fluids **20**, 123304 (2008).  
 Subramanian and Koch JFM, **632**,359 (2009)

- An active suspension of elongated swimming pushers is **linearly instable** at all concentrations

# An heuristic view

Velocity shear mode



Subramanian and Koch JFM, **632**,359 (2009)

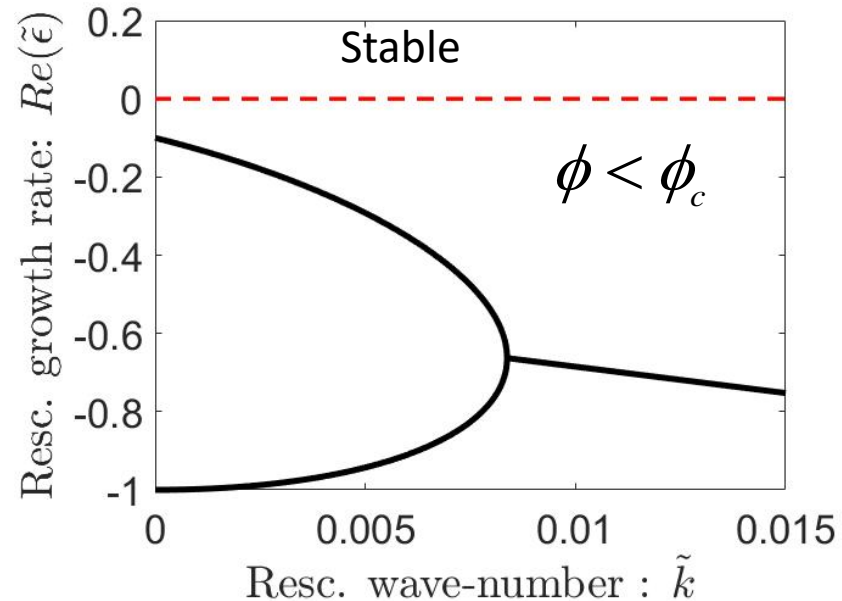
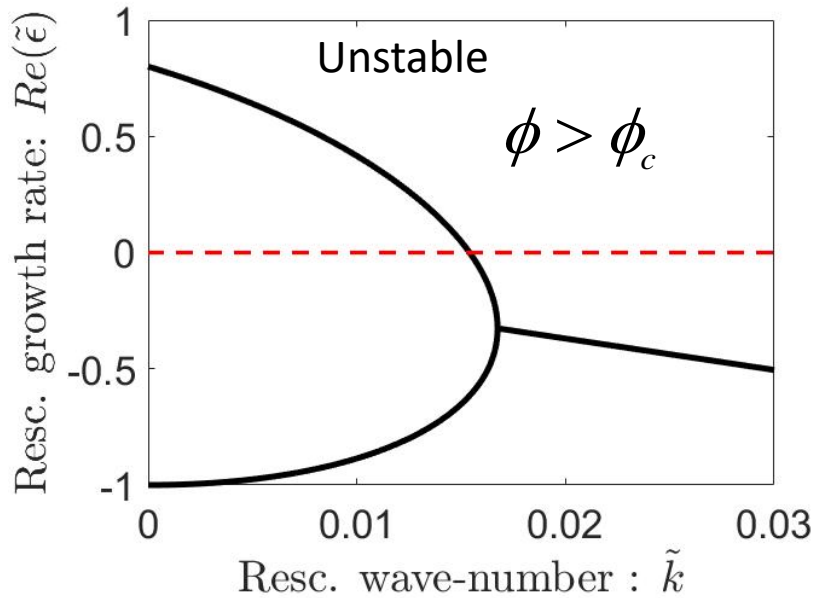
# Rotational noise $D_r \propto 1/\tau_p$

Activity number  $A = \frac{\sigma_0}{\eta_0 D_r l^3} \propto \frac{V_B}{D_r l} \propto \frac{V_B \tau_p}{l} = l_p / l$

$\tau_p$ : directional persistence time  
 $l_p = V_B \tau_p$ : persistence length

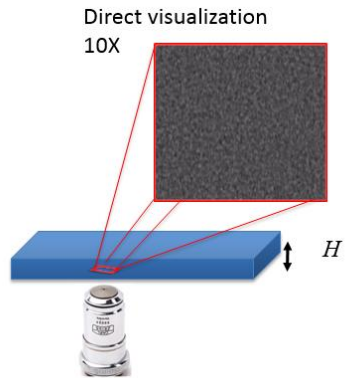
Linear instability

$$\phi_c \propto 1/A = l/l_p$$

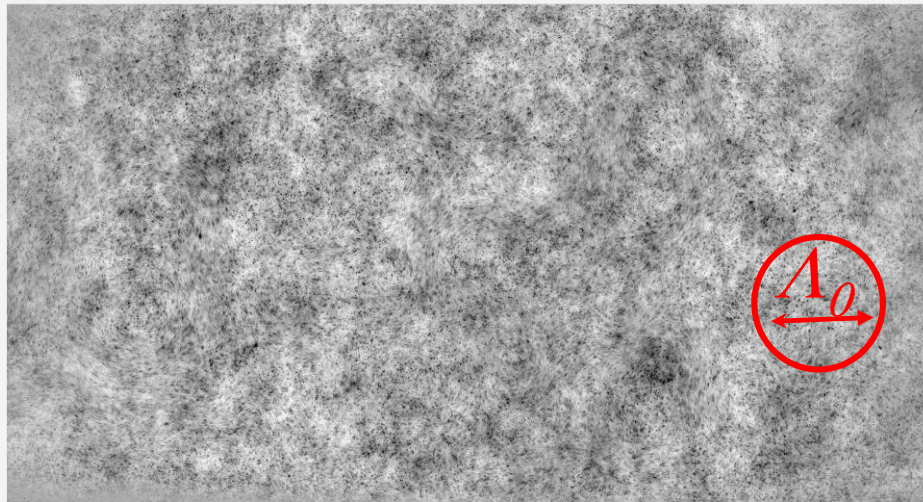


□ Rotational noise stabilizes the suspension below a critical volume fraction  $\phi_c$

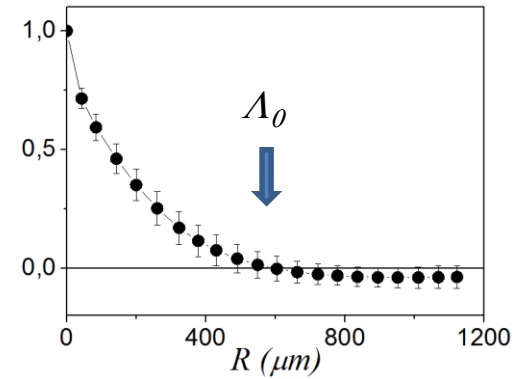
# Collective motion of E.coli



$H=600 \mu m$



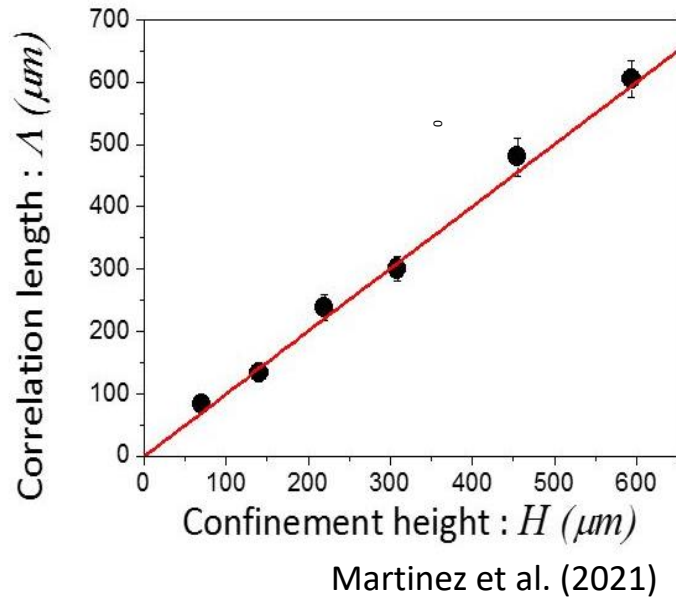
Velocity correlation



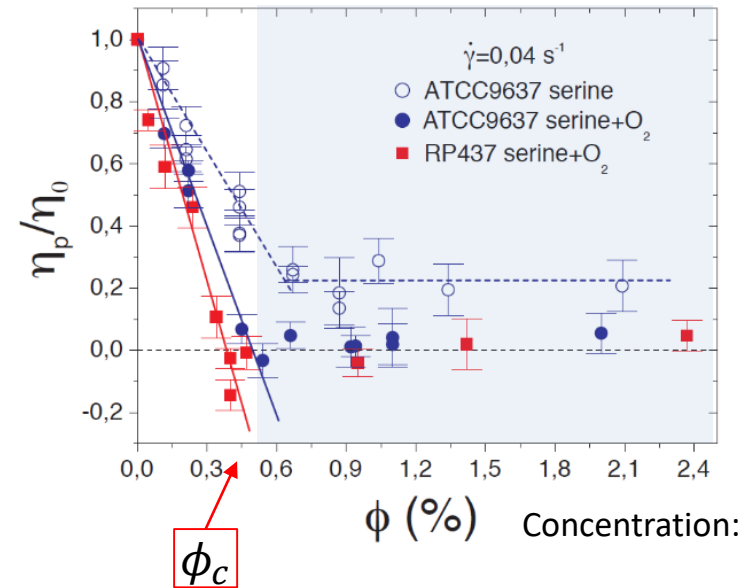
Vortex scale  $\Lambda_\theta(H)$  ?

- Emergence of large scale vortices in dense suspensions of motile E.coli

# Emergence of a critical « superfluid »

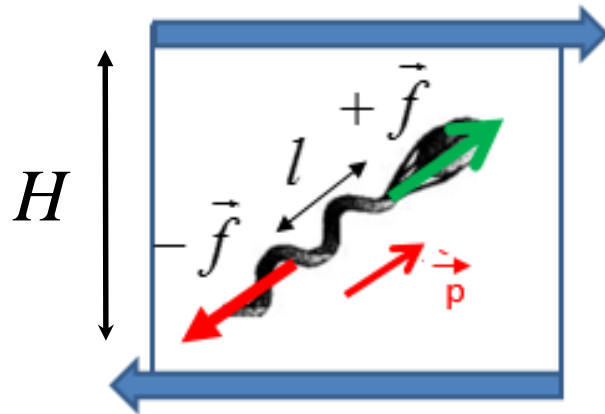


Viscosity Lopez et al. PRL. **115**, 028301 (2015)



- ❑ Correlation length  $\Lambda_0$  increases linearly with confinement height  $H$
- ❑ The fluid becomes « critical »
- ❑ Macroscopic viscosity can reach zero !

# Viscosity decrease with concentration



## Heuristic view

Y.Hatwalne *et al*, Phys. Rev. Lett. **92**, 118101 (2004)

Relative viscosity at low shear rate

$$\eta_r = 1 + (a - b \frac{V_B \tau_p}{l}) \phi$$

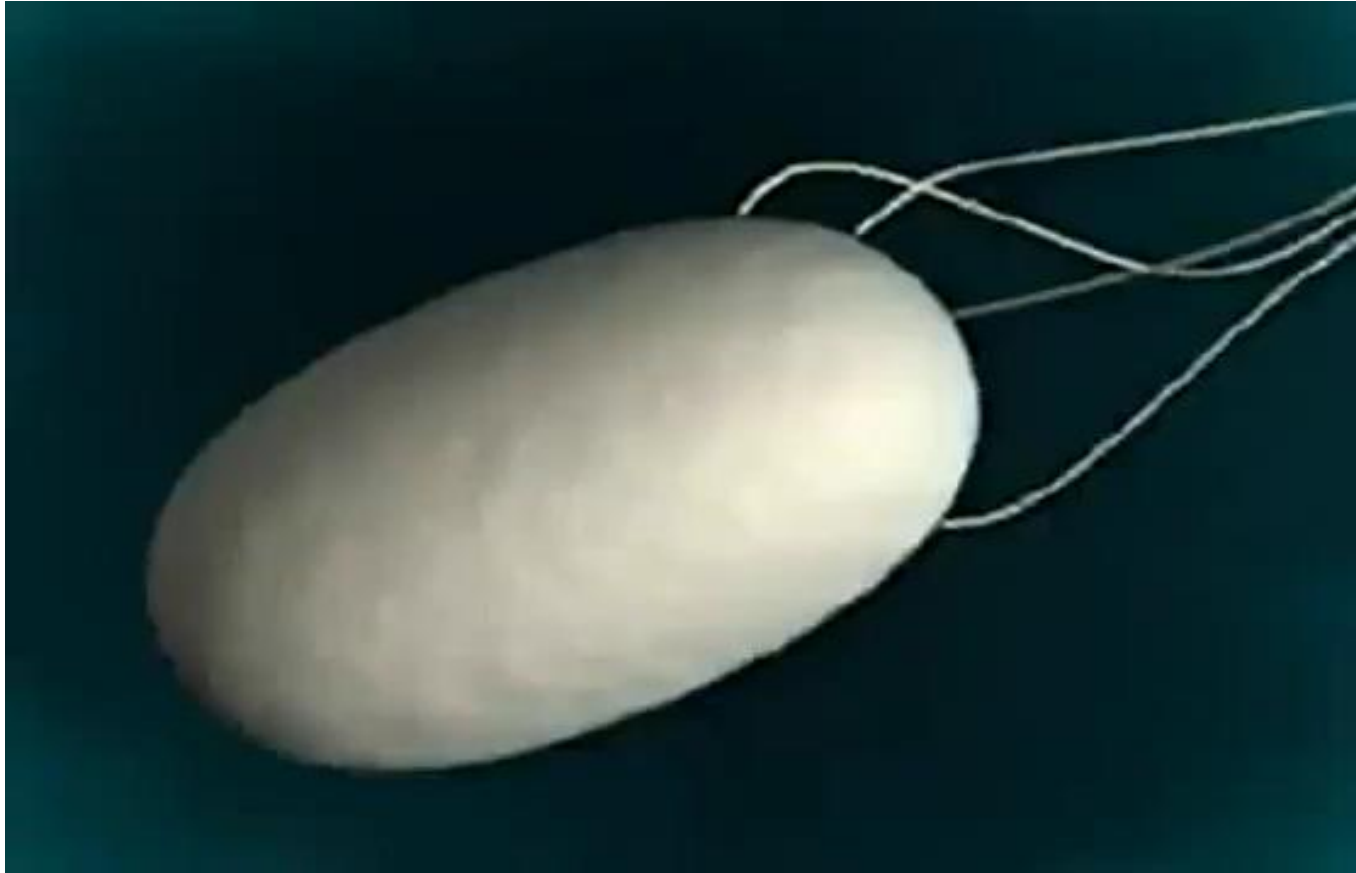
B. M. Haines *et al.*, PR E **80**, 041922 (2009).

D.Saintillan, Model Exp. Mech. **50**, 1275 (2010).

Activity number  $A = l_p/l$

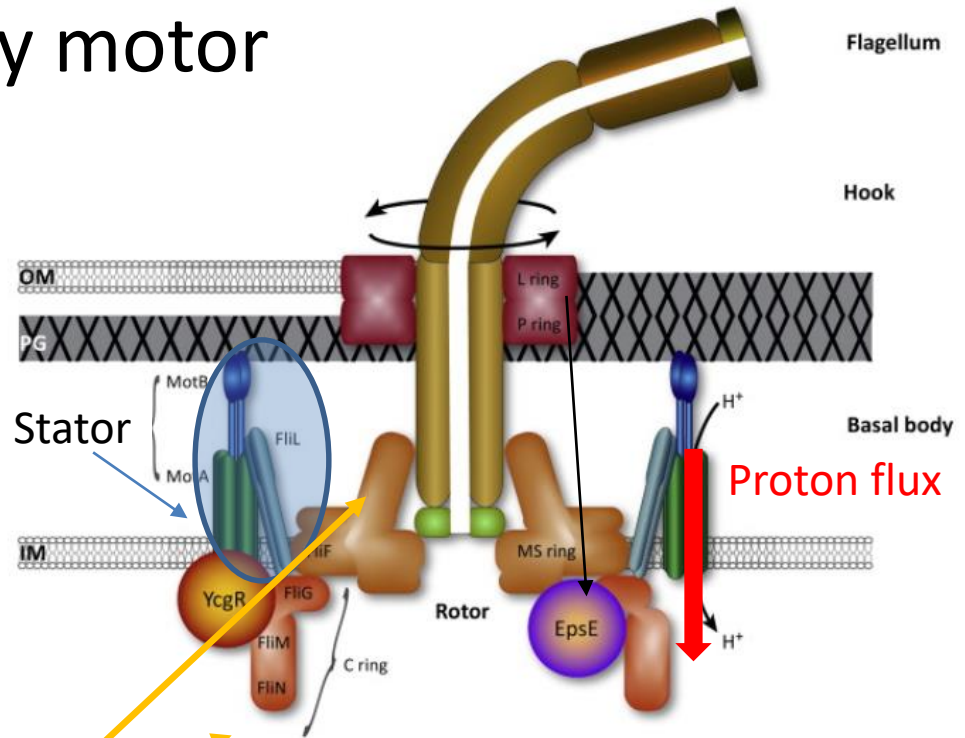
- ❑ Zero viscosity at  $\phi = \phi_c$  predicted by active pushers dipoles hydrodynamic model (but for  $\phi > \phi_c$  ???)

What is under the hood ?



# The rotary motor

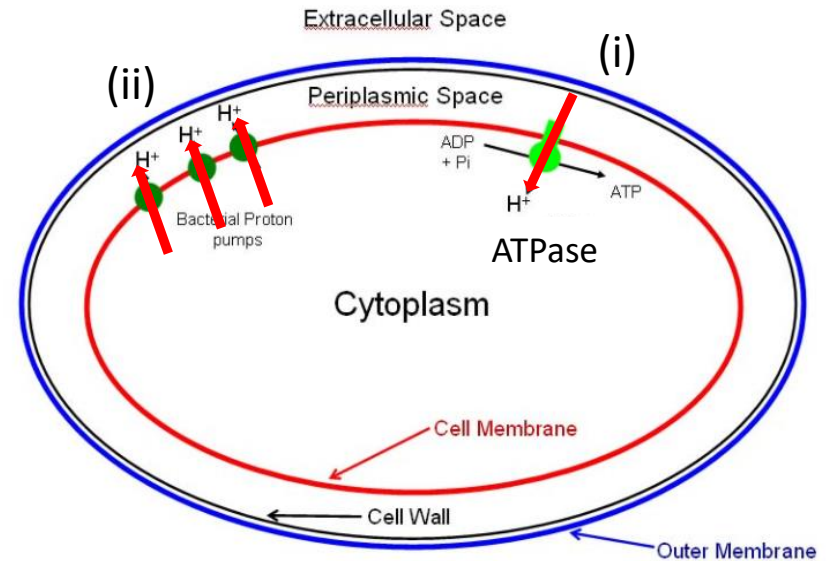
Rotation rate :  $100-200\text{ Hz}$



Rotor

(i) Proton gradient motor

(ii) Proton pumps



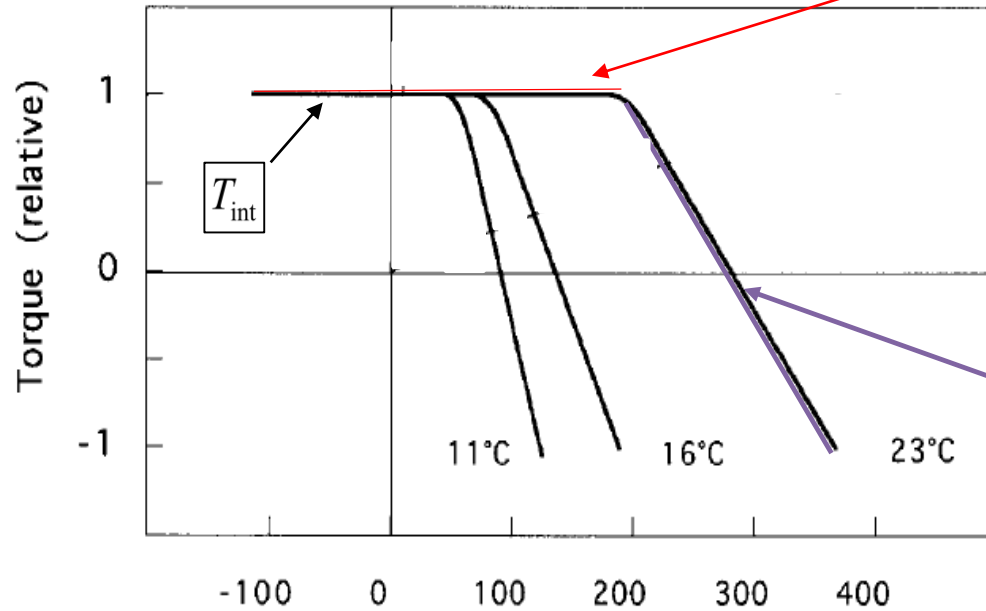
Berg, Annu. Rev. Biochem. **72**, 19 (2003)



# Rotary motor performances

E.coli  $T_{max} \approx 5 \cdot 10^3 \text{ pN} \cdot \text{nm}$

Stall torque regime

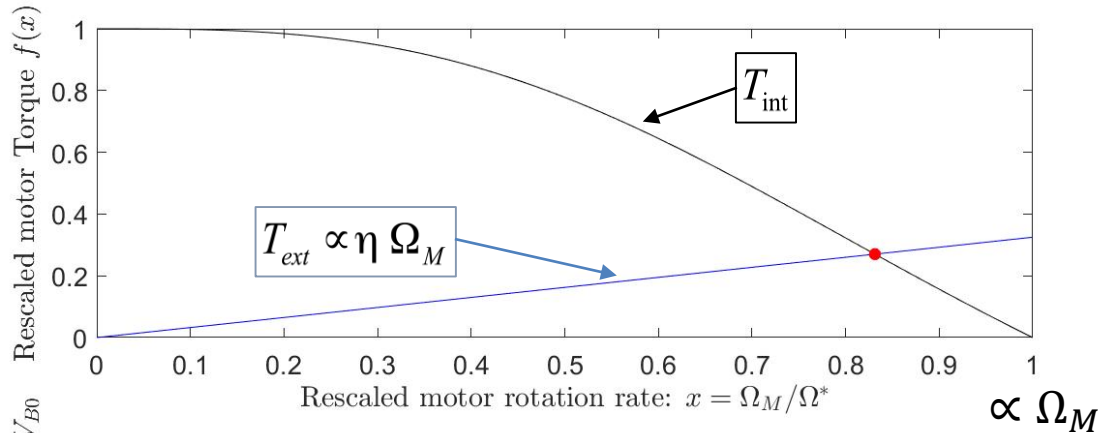


Motor rotation rate  $\Omega_M$  (Hz)

Berg and Turner, Biophys.J. 65, 2201 (1993)

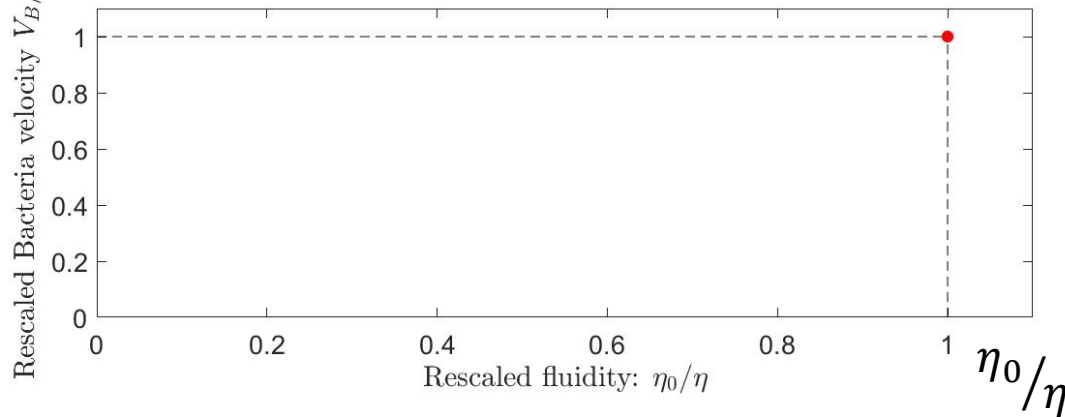
# Swimming velocity dependence on viscosity $\eta$

$$f(x) = \frac{T_{int}}{T_{max}} \quad \text{Relative torque}$$



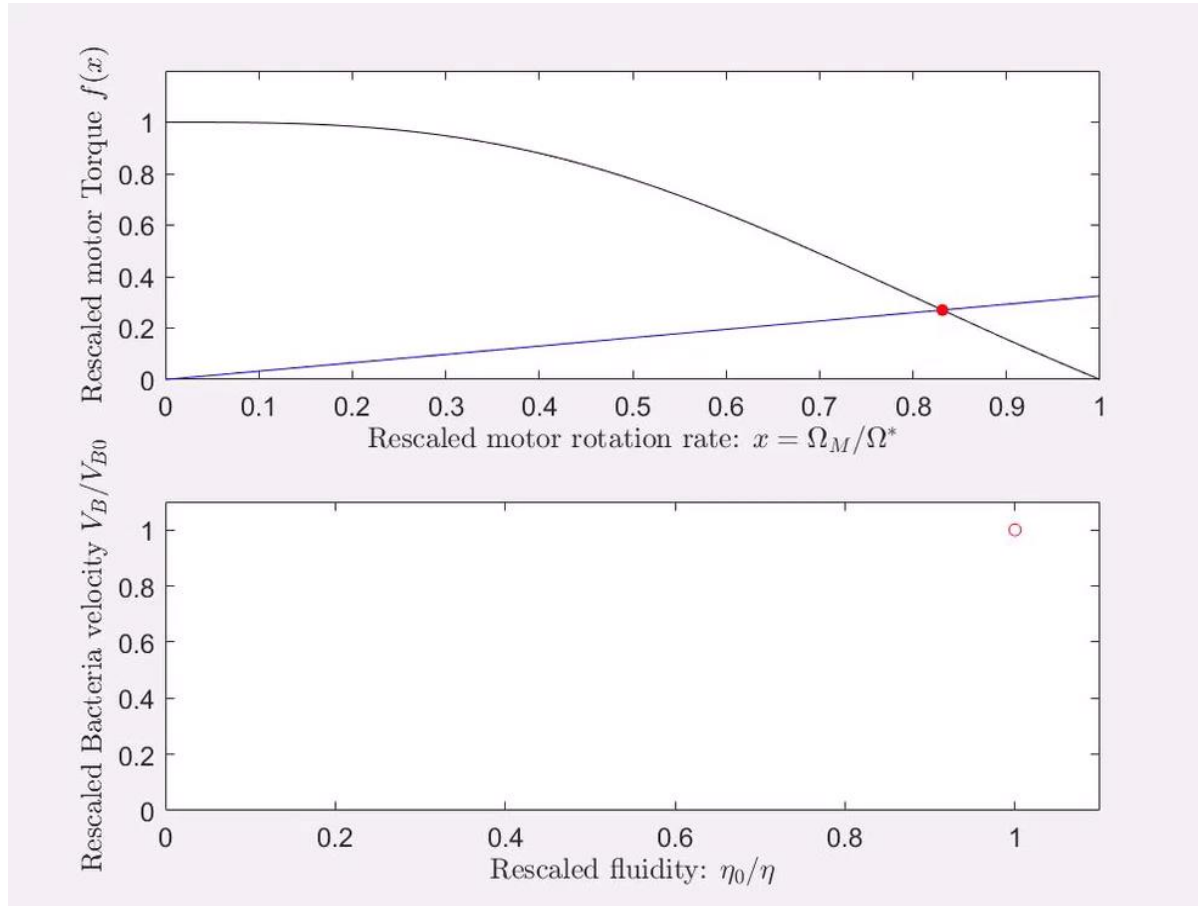
Relative motor rotation rate

$$\frac{V_B}{V_B^0}$$

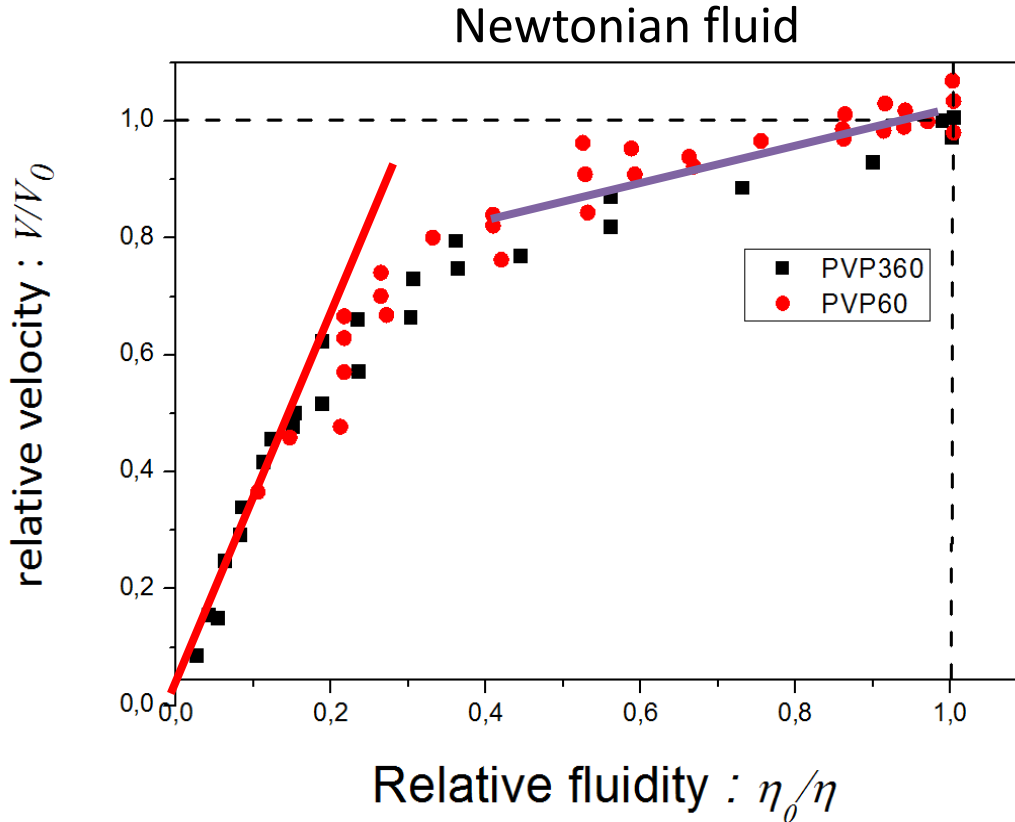


Relative fluidity

# Swimming velocity dependence on viscosity $\eta$



# Swimming velocity dependence on viscosity $\eta$

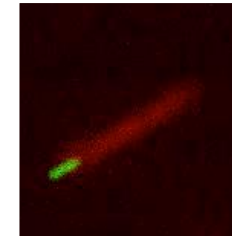
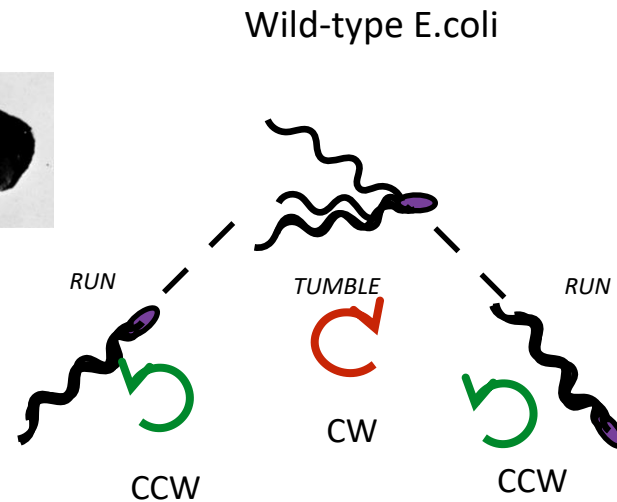


After Martinez et al.  
PNAS , **111**, 17775 (2014)

□ Nominal regime : weak dependence

□ Stall torque regime :  $V_B \propto \Omega_M \propto \frac{T_{max}}{\eta}$

# Run and tumble process

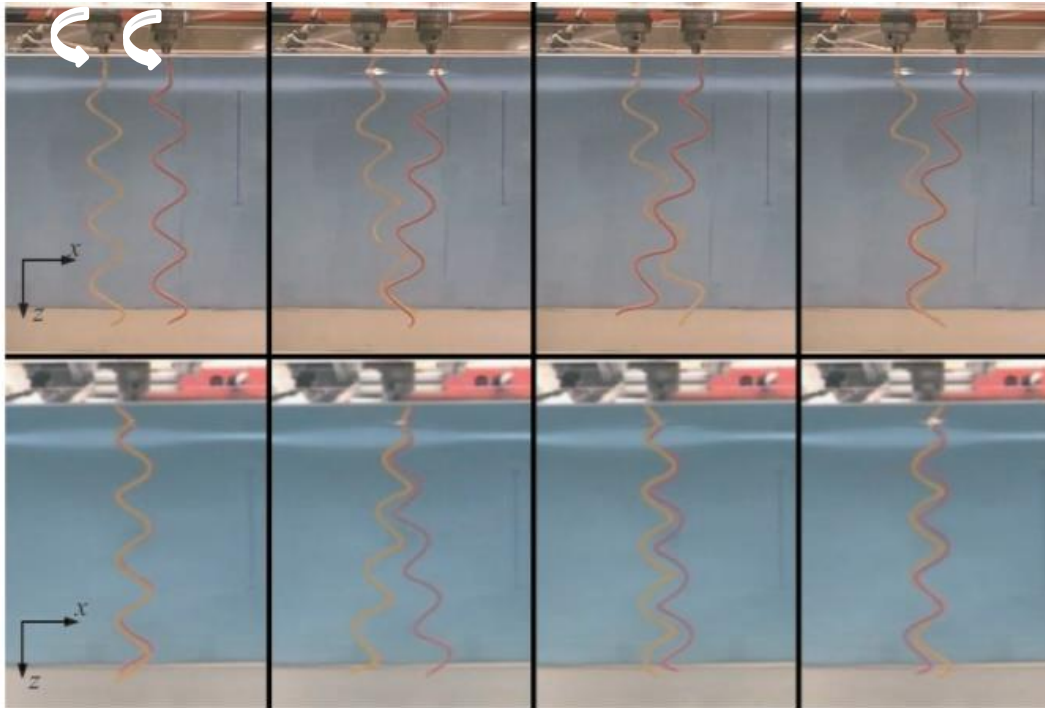


Wild type E.coli RP437

- Alternated switches in motor rotation create stochastic bundling / unbundling processes
- Explore the environment as a random walk
- Bias of the random walk in presence of chemical gradients (**chemotaxis**)

# Hydrodynamic bundling process

E.Coli – "petricious" - 4 – 5 helical flagella

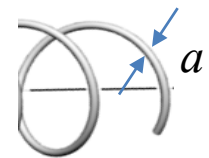


$$R_e \cong 10^{-3}$$

$$M = \tau\omega = \frac{\eta L^4}{K} \omega \cong 150$$

Bending modulus

$$K = EI \propto a^4$$

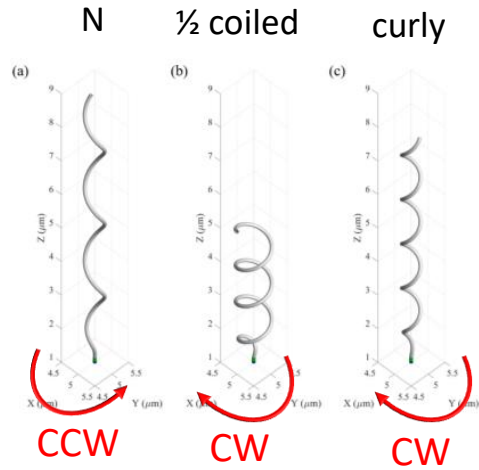


B. Liu et al. PNAS , **108**, 19516 (2011)

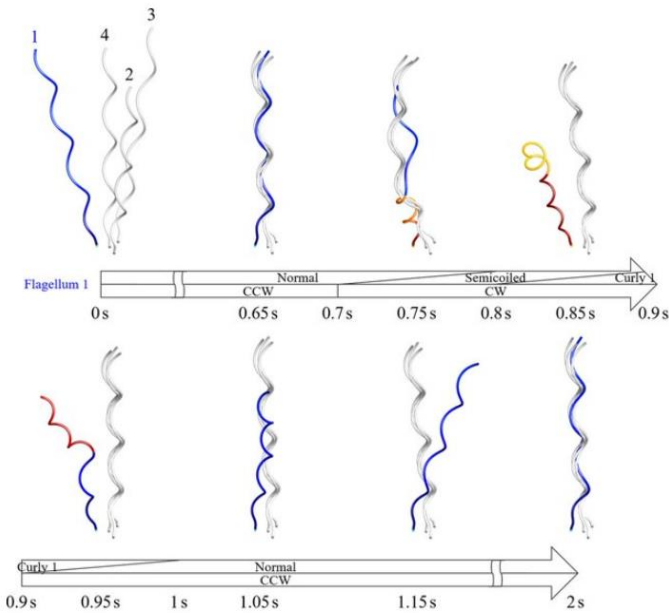
□ Hydrodynamic attraction between rotating flagella => bundling

# Polymorphic transformation

Turner et al. J. Bacteriology, **182**, 2793 (2000)



G.Miño PMMH-ESPCI

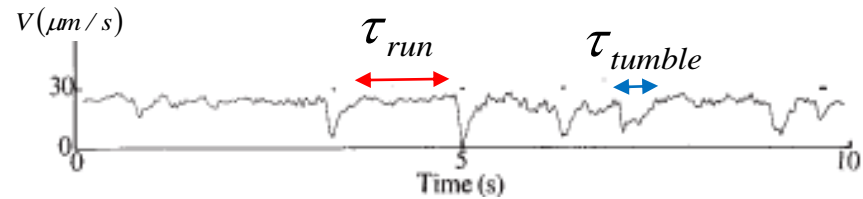
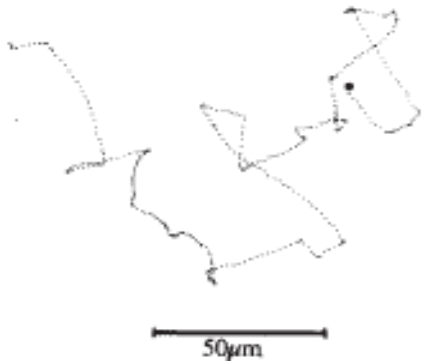


Lee et al. PRE **98**, 052405 (2018)

Change shape =>  
change of swimming direction

# Standard vision for the run and tumble process

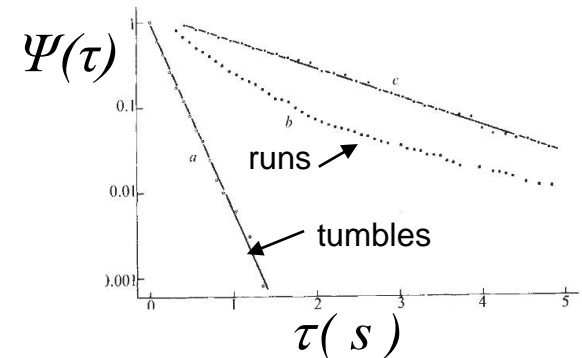
Lagrangian 3D tracking



Berg & Brown, Nature **239**, 500 (1972)

Fraction of time run  $> \tau$

$$\Psi(\tau) = 1 - \int_{\tau}^{+\infty} \Pi(\tau') d\tau'$$



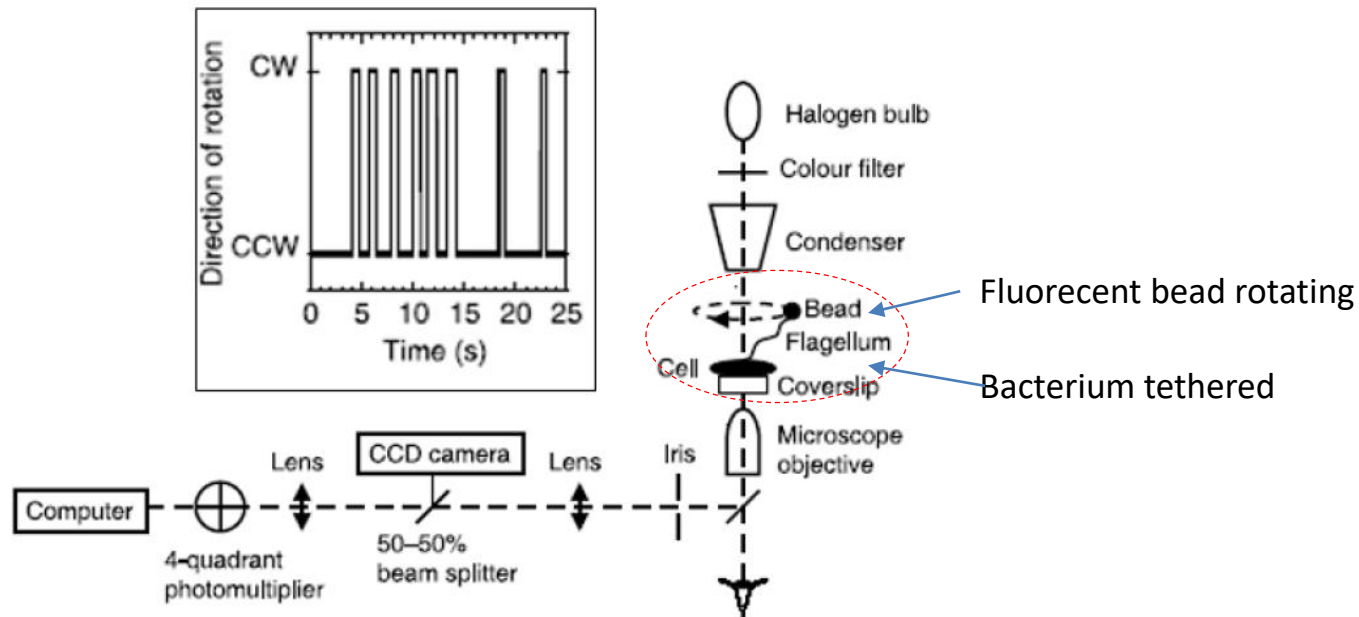
□ Poisson processes (currently assumed)

$$\Pi(\tau) \propto \exp(-\tau / \tau_{\alpha}) \begin{cases} \tau_{run} \cong 1s \\ \tau_{tumb} \cong 0.1s \end{cases}$$

Berg, *Ecoli-in-motion* (2004)



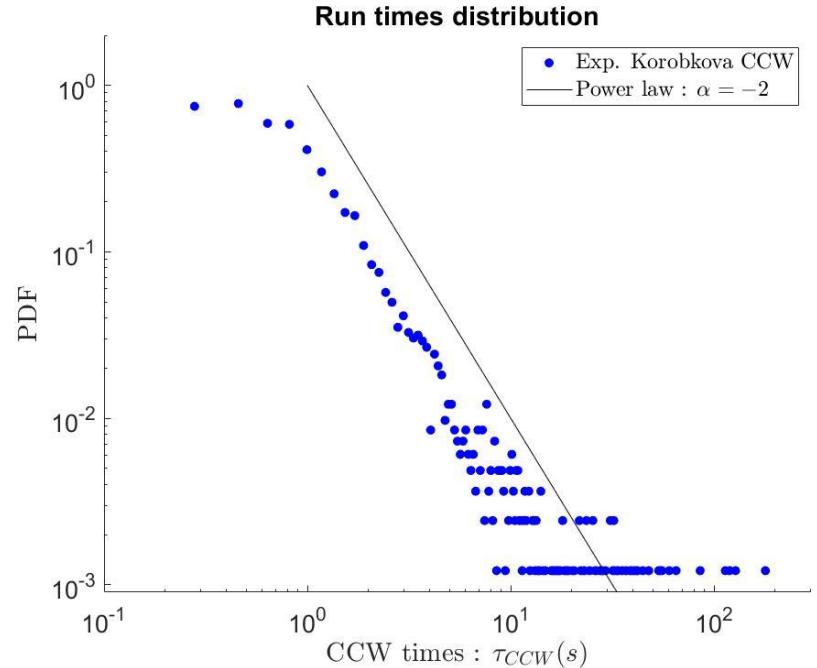
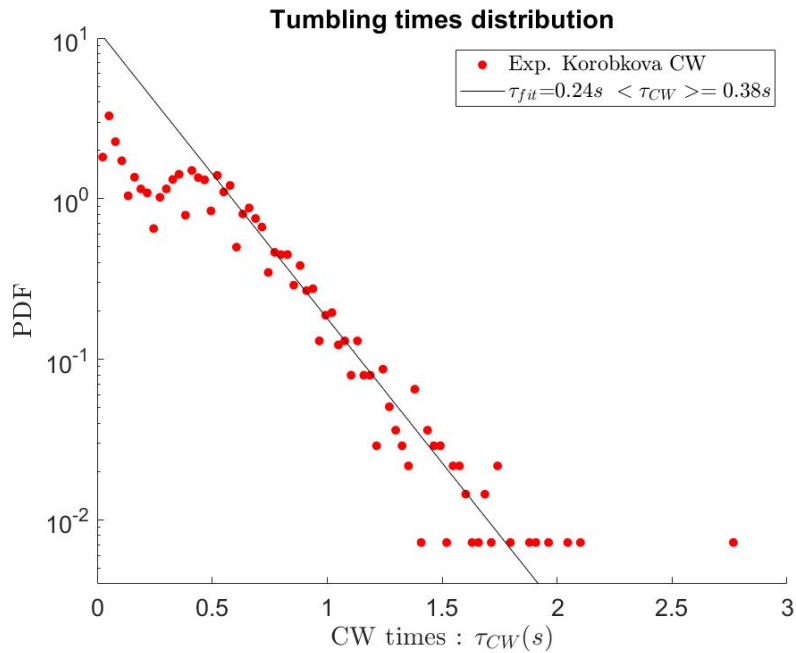
# Switch times distributions



Korobkova *et al.*, Nature, **428**, 574, 2004

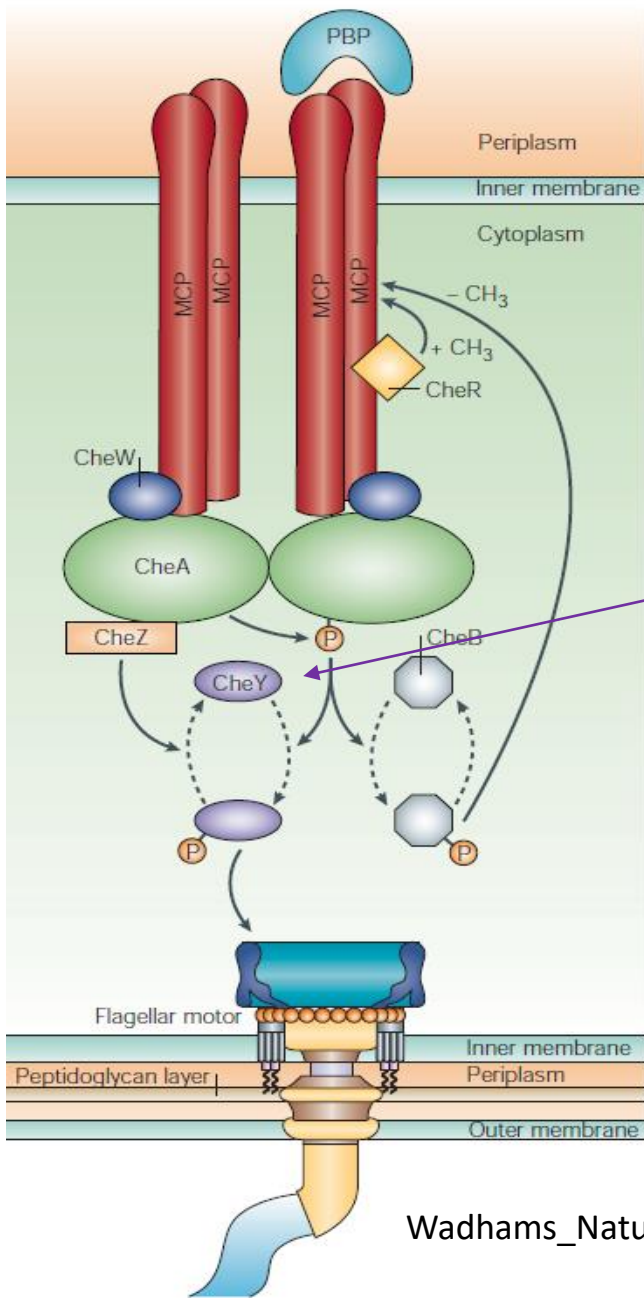
□ Obtain the distribution of run (CCW) times and tumbling (CW) times

# Switch times distributions



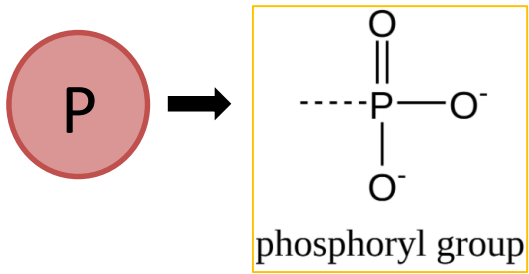
- ❑ Tumbling times displays an exponential tail
- ❑ Large tail «run – time » distributions
- ❑ At odd with simple Poisson R/T statistics

# Chemotactic biological machinery

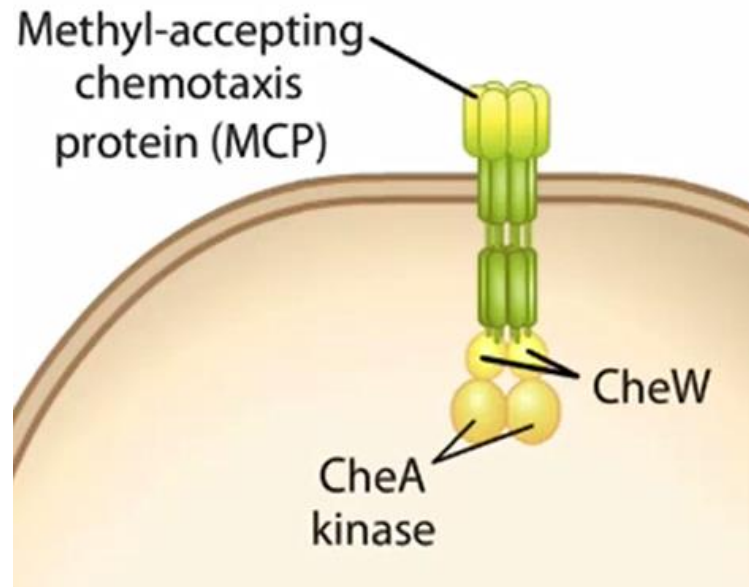


MCP : Methyl-accepting Chemotaxis Proteins

CheA, CheW  
**CheY**, CheB, CheR  
 Functional proteins

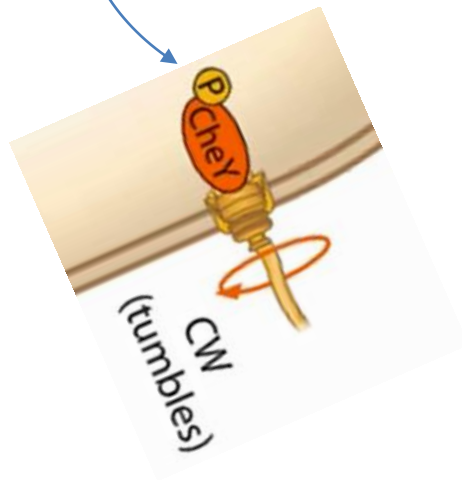
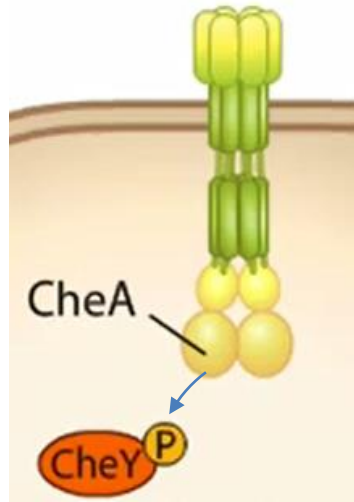


Rotary motor



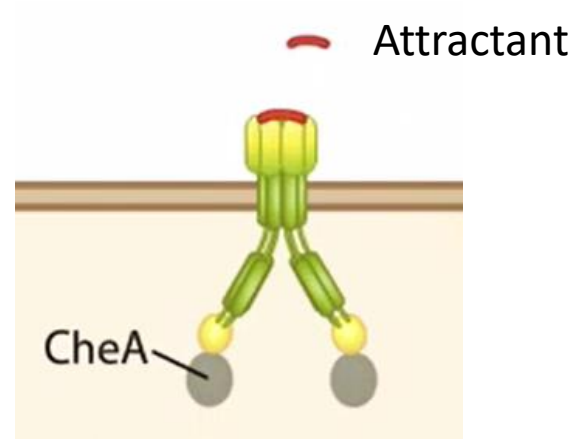
CheA = Kinase protein = cut ATP and releases P

### MCP active state



Promotes **tumbling** phase

### MCP passive state



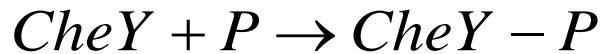
no P release



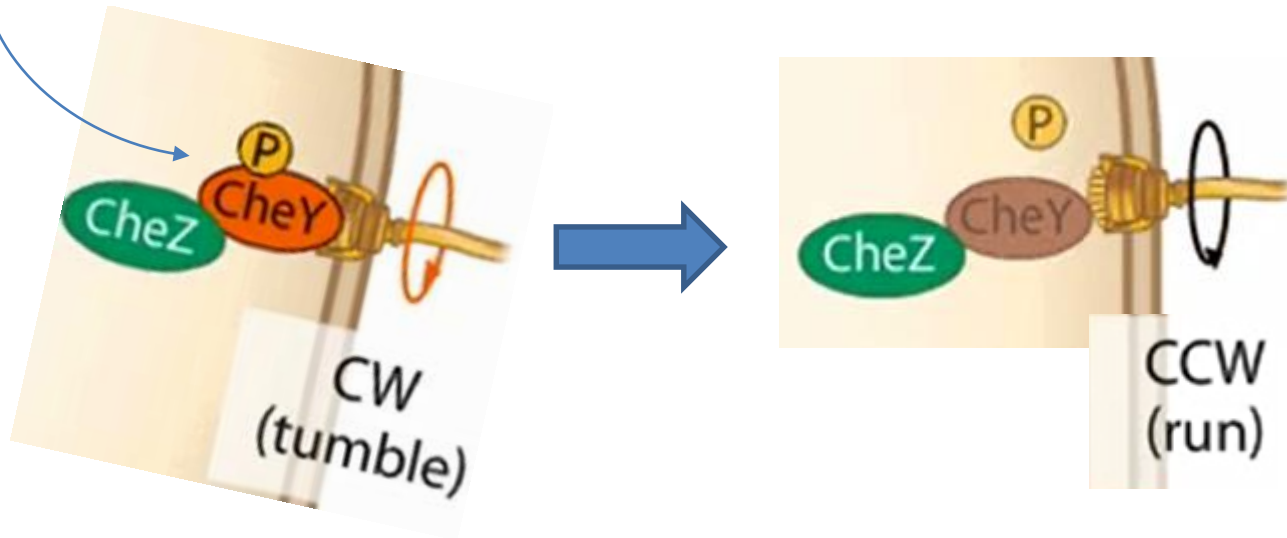
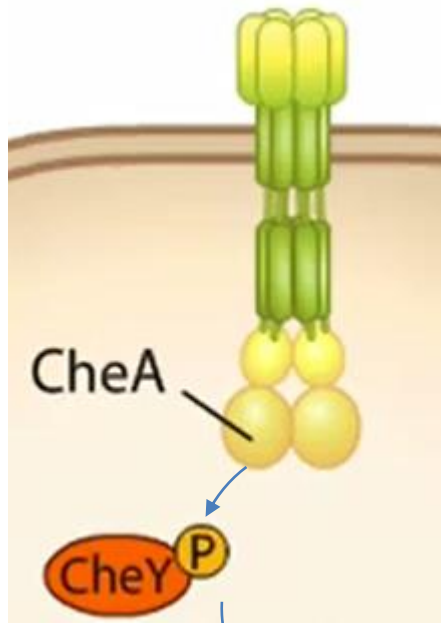
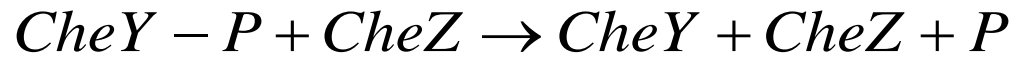
Promotes **run** phase

# Adapted bacterium

CheY phosphorylation from the CheA production of P

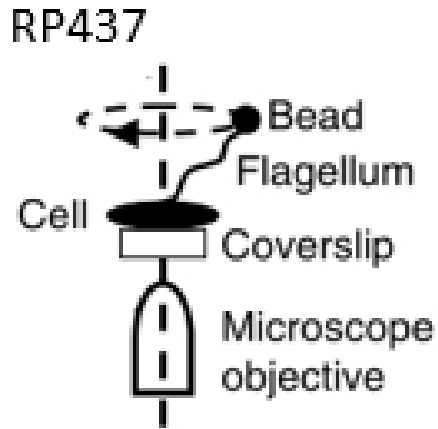


CheY de-phosphorylation by CheZ



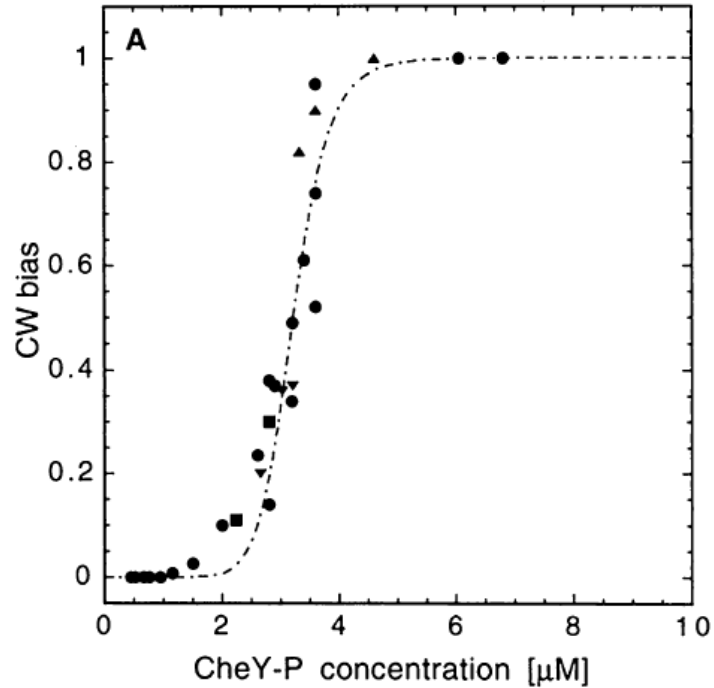
- ❑ An adapted bacterium undergoes phosphorylation / dephosphorylation of CheY, hence fixing the run/tumble rate

# Switching sensitivity to CheY-P



Tumble mode

Run mode

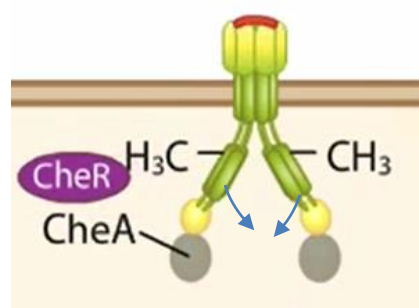
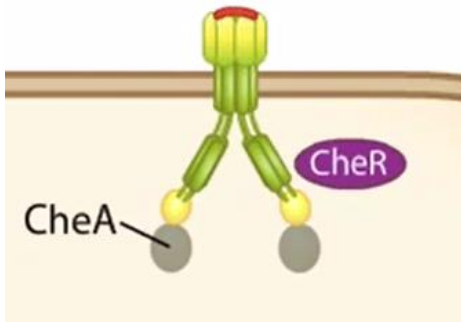


Cluzel et al. Science **287** 1655 (2000)

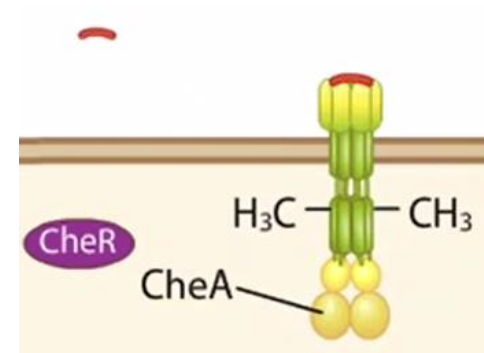
□ **Highly sensitive** to the presence of CheY-P near the motor

# Sensory adaptation process

MCP passive state



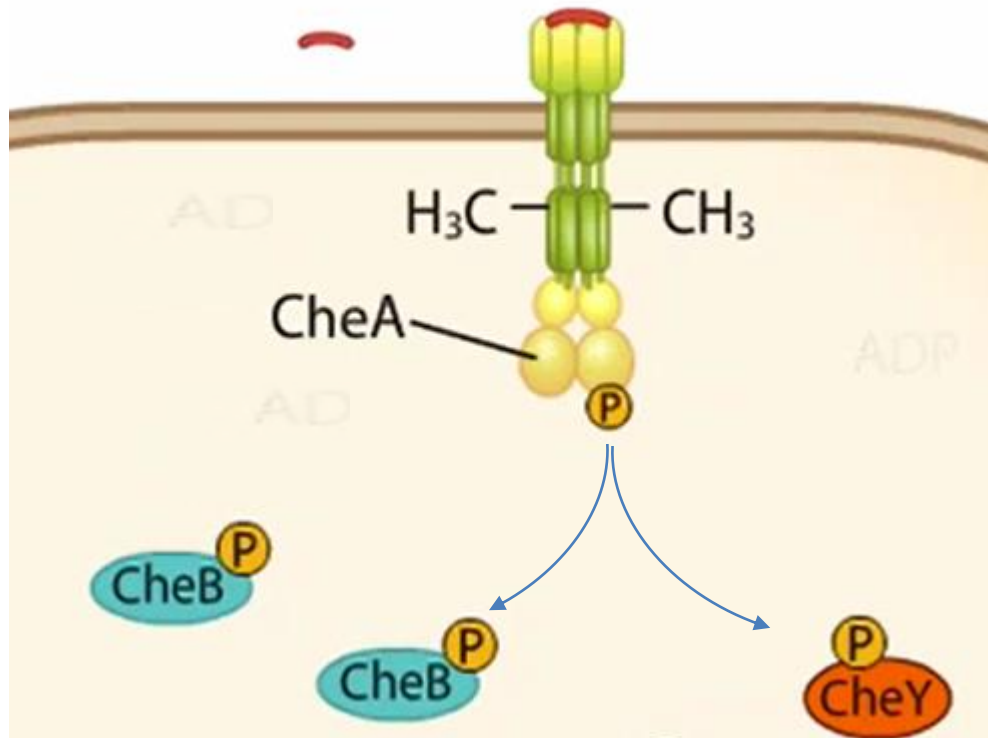
MCP active state



- ❑ CheR slowly methylates MCP such as to reach an active state
- ❑ At high level of methylation the bacterium is re-adapted and run/tumble exploration resumes

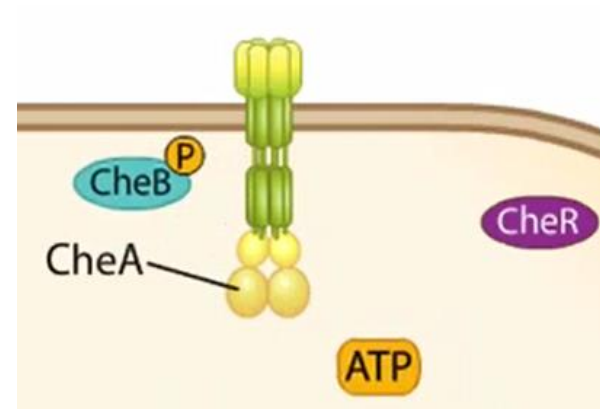
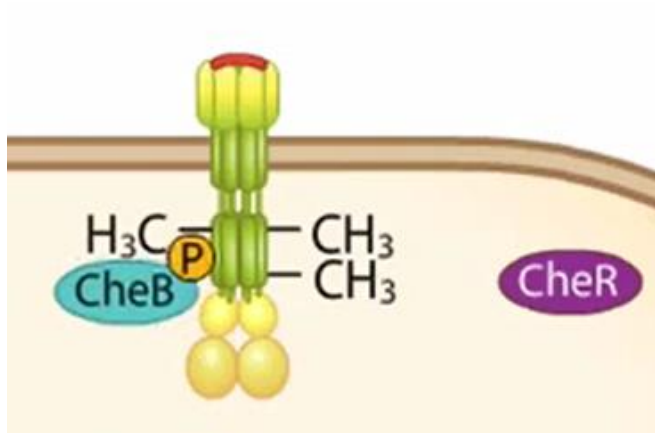


# Regulation process



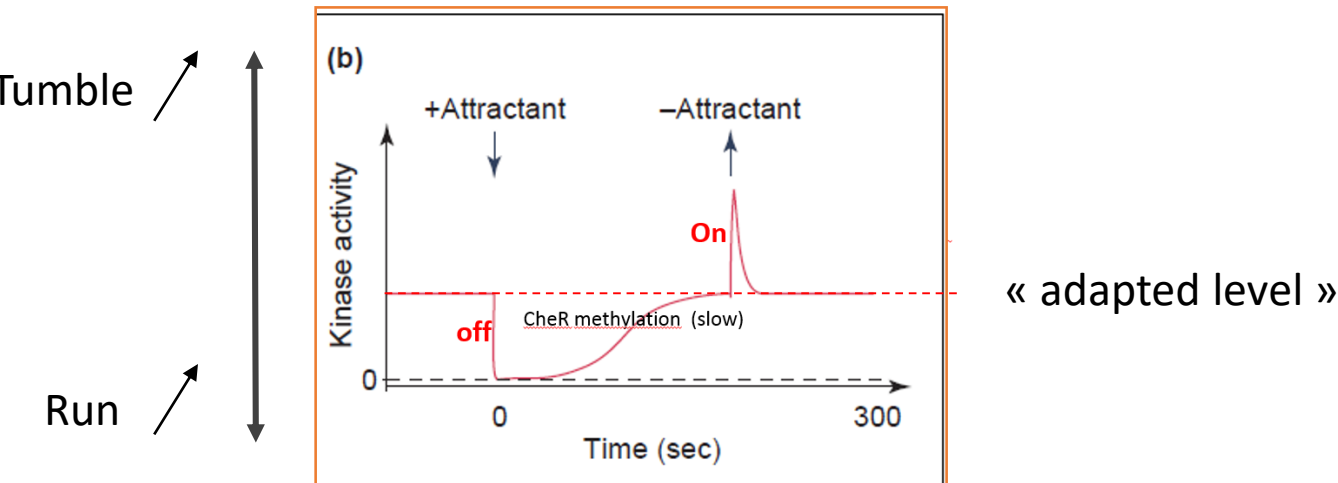
- ❑ CheY competes with CheB for the P from kinase CheA

# Regulation process



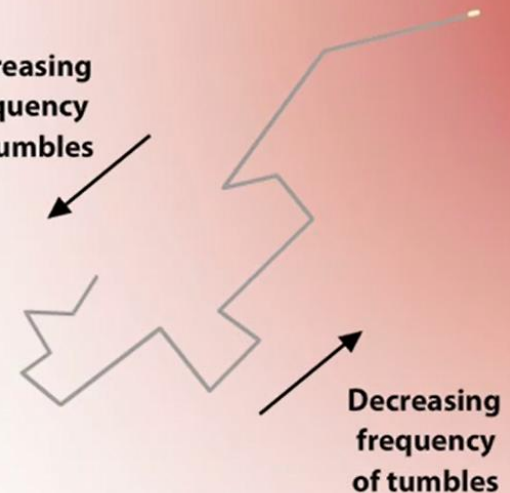
- ❑ CheB-P opposes the activity of CheR and **de-methylates** MCP
- ❑ In **lower attractant regions** **CheR is less likely to methylate** MCP then CheB-P demethylation dominates and the bacterium is re-adapted at low methyl level

# Regulated chemotactic response

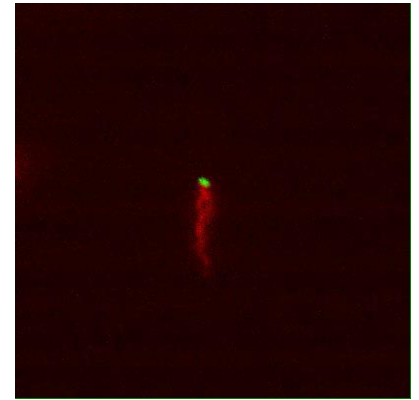
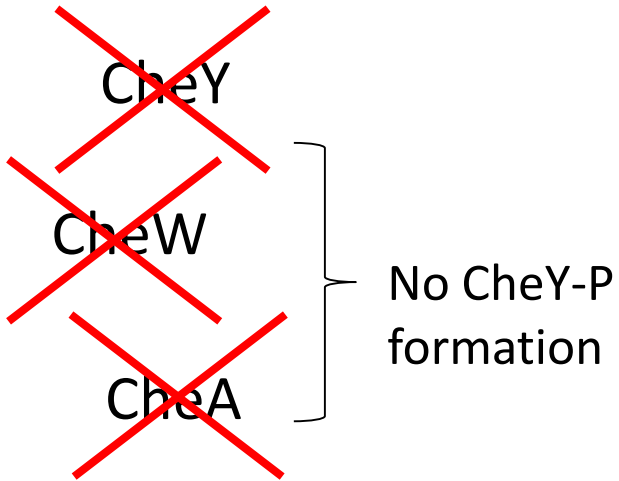


- ❑ High attractant level: decreases tumble frequency
- ❑ Low attractant level : increases tumble frequency

Increasing frequency of tumbles



# Mutant swimmers

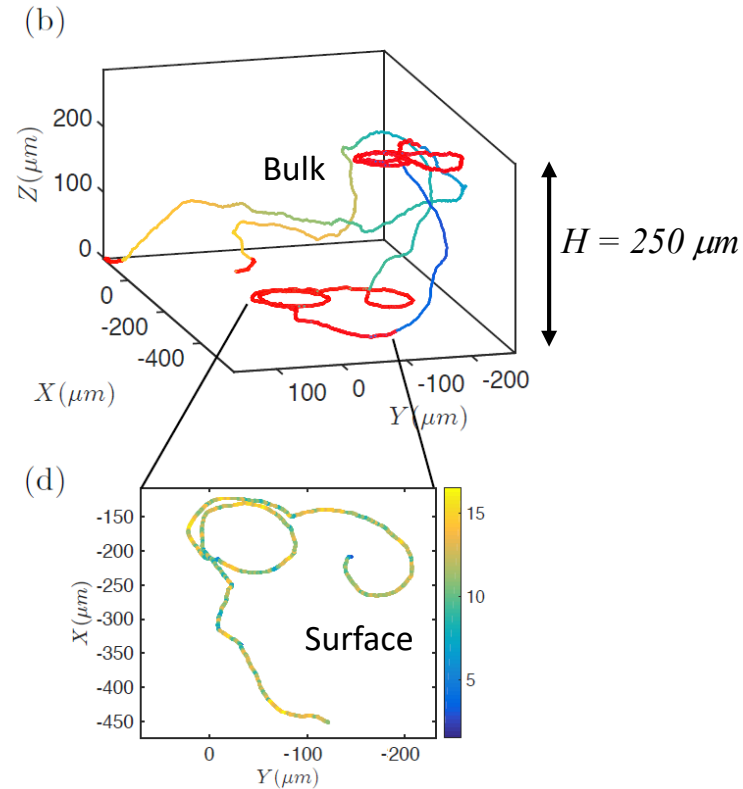
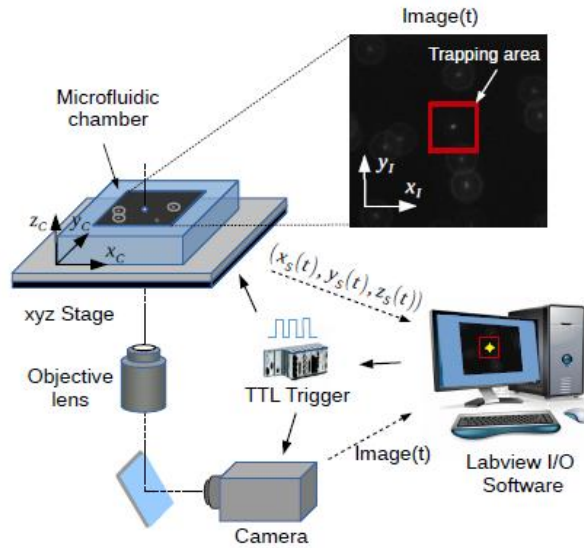


Smooth runner



Tumbler swimmer

# Automated 3D lagrangian tracking



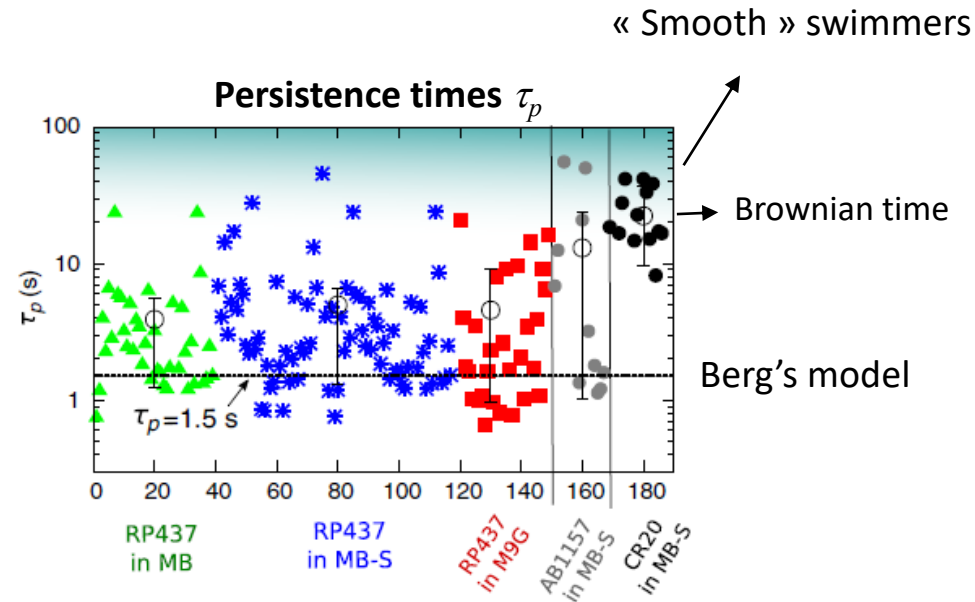
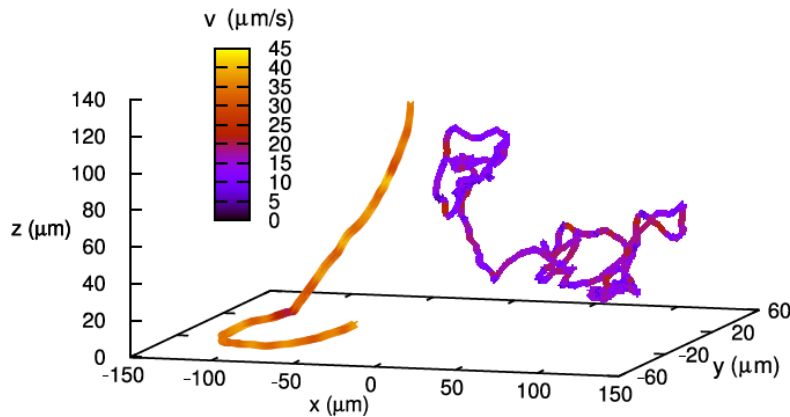
Darnige, Figueroa-Morales et al. Rev.Scient.Instr. **88**, 055106 (2017)  
Junot et al. preprint (2021)

- ❑ Long time tracks ( $> 20$  min) of fluorescent E.coli bacteria swimming between two glass plates
- ❑ Extract trajectories at surfaces and in the bulk

# Motility features in a population of monoclonal WT E.coli

N. Figueroa-Morales et al Phys.Rev.X, **10**, 021004 (2020)

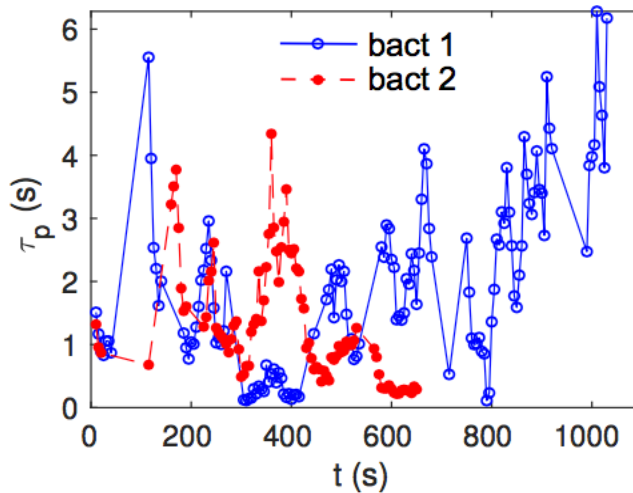
Visualization over **short-times** (<100 s)



- ❑ Very large distribution of persistence times  $\tau_p$
- ❑ Robust to environmental and E.coli strain changes

# Behavioral variability

Visualization over very long times (up to 25 min)

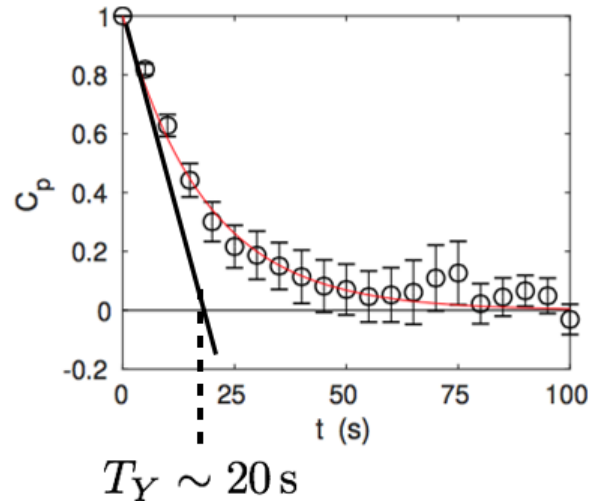


Never tumbles: high  $\tau_p$

Often tumbles: low  $\tau_p$

- ❑ Persistence time  $\tau_p$  varies widely in time for the **same** bacterium

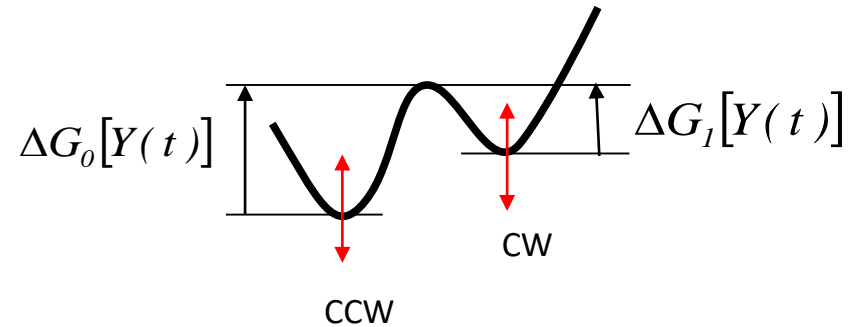
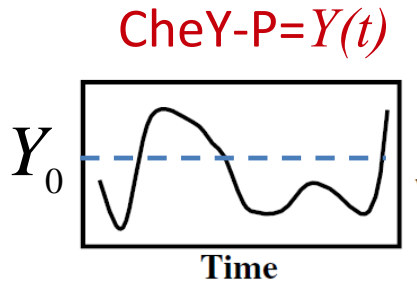
# Persistence time auto-correlation



- The persistence time  $\tau_p$  for a bacterium is correlated over a memory time:  $T_Y \sim 20$  s



# Modeling fluctuations in R/T regulation



Orstein-Uhlenbeck equation  
for CheY-P concentration :

$$\dot{Y}(t) = -\frac{(Y - \bar{Y})}{T_Y} + \eta(t)$$

White noise

$T_Y$  Memory time

$T_Y$

Tu and Grinstein, PRL **94**, 208101 (2005)

- Reaction barriers for the phosphorylation reaction process vary with fluctuating CheY\_P concentration

# Behavioral Variability Model

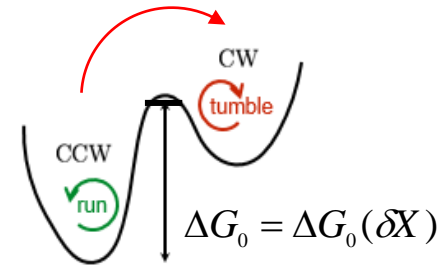
N. Figueroa-Morales et al Phys.Rev.X, **10**, 021004 (2020)

Collab. with R. Soto Univ. Chile

$$\delta X \propto [CheY - P]$$

Relative fluctuations in CheYP: the « mood »

$$\frac{\Delta G_0[Y(t)]}{k_B T} \approx \frac{\Delta G_0[Y_0]}{k_B T} + \Delta_0 \delta X(t) + \dots$$



Switching rate run (CCW) to tumble (CW) :  $\frac{1}{\tau_s} \approx \frac{1}{\tau_0} \exp(\Delta_0 \delta X(t))$

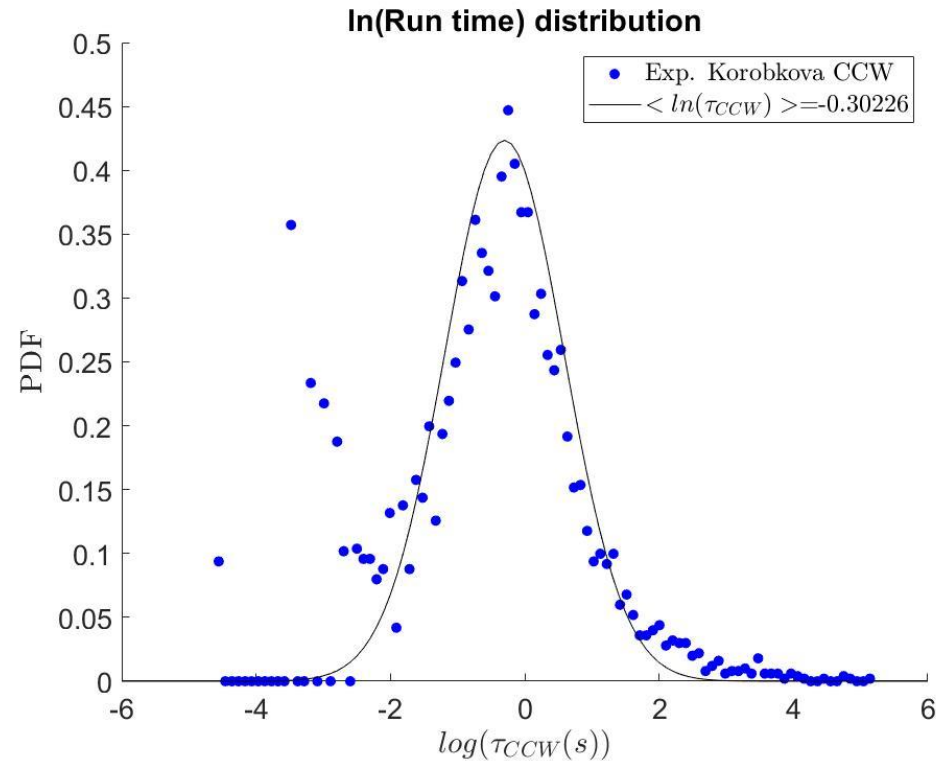
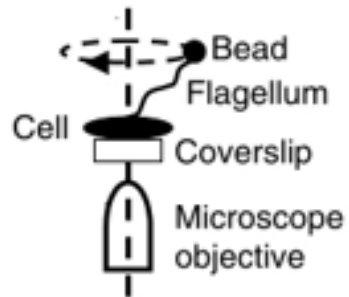
$$\ln(\tau_s/\tau_*) \propto \delta X(t)$$

Normal Gaussian distribution  
(Orstein Uhlenbeck process)

□ CCW->CW switching times follow a **log-normal distribution**

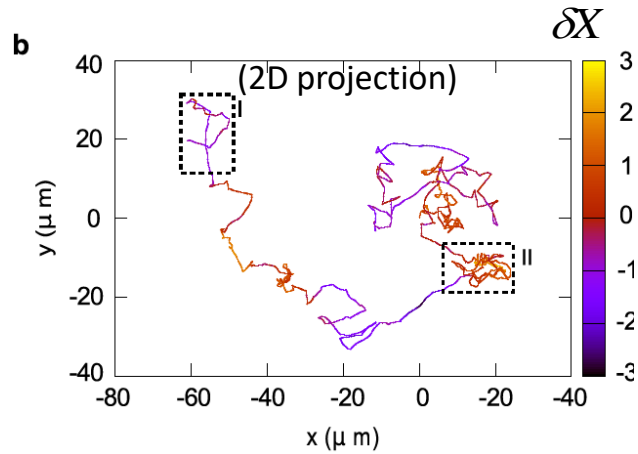
# Back on Korobkova's data

RP437

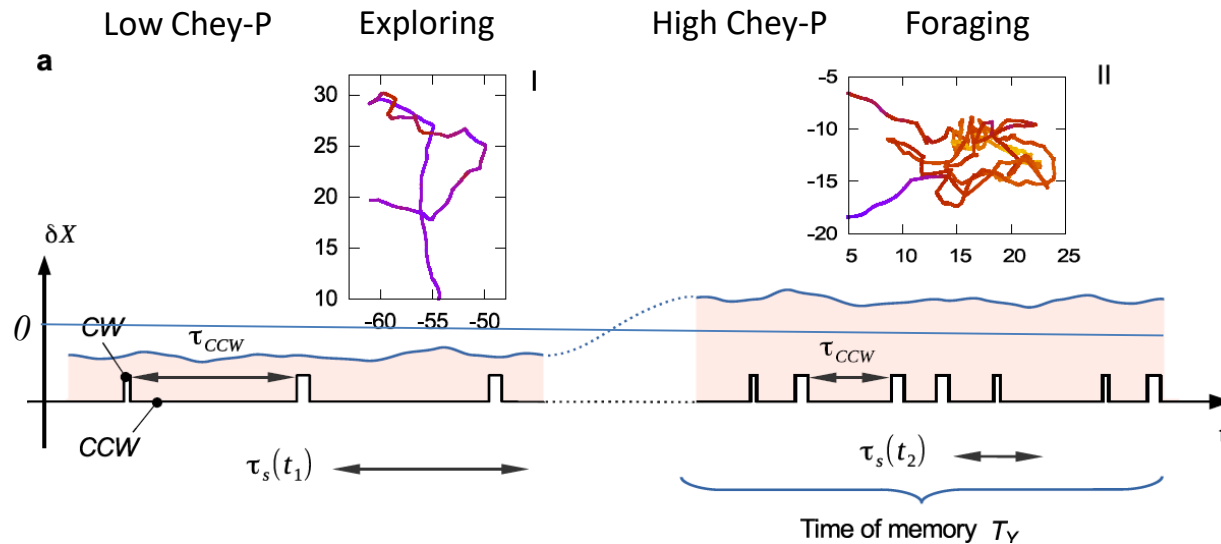


- CCW- $\rightarrow$ CW single cell time series consistent with a **log-normal distribution**

# In the « mood » for walk



Bacteria motility individually controlled by **CheY-P fluctuations** : « the mood »



□ Emergence of a random walk with memory



